# **SIEMENS**

# MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST

**Operating Instructions** 

Issue 06/04



User Documentation 6SE6400-5CC00-0BP0

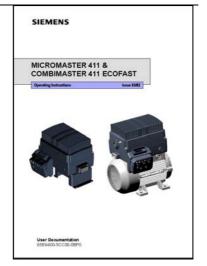
### **MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST**

### **Getting Started Guide**

Provides for Quick Commissioning of the Inverter.

### **Operating Instructions**

Gives information about features of the MICROMASTER 411 ECOFAST and COMBIMASTER 411 ECOFAST, Installation, Commissioning, Control modes, System Parameter structure, Troubleshooting, Specifications and available options of the units.



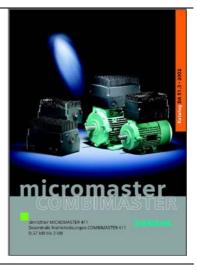
### **Parameter List**

The Parameter List contains the description of all Parameters structured in functional order and a detailed description. The Parameter list also includes a series of function plans.



### **Catalogues**

In the catalogue you will find all the necessary information to select an appropriate inverter, as well as Operator Panels and Communication Options.



# **SIEMENS**

# MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST

Operating Instructions Anwender-Dokumentation

Valid for Release Issue 06/04

Inverter Type Control MICROMASTER 411 ECOFAST & Version COMBIMASTER 411 ECOFAST 1.2

Overview	1
Installation	2
Commissioning	3
System Parameters	4
Troubleshooting	5
Specifications	6
Options	7
Electro-Magnetic Compatibility	8
Appendix	A B

Further information is available on the Internet under: http://www.siemens.de/micromaster

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Other functions not described in this document may be available. However, this fact shall not constitute an obligation to supply such functions with a new control, or when servicing.

We have checked that the contents of this document correspond to the hardware and software described. There may be discrepancies nevertheless, and no guarantee can be given that they are completely identical. The information contained in this document is reviewed regularly and any necessary changes will be included in the next edition. We welcome suggestions for improvement.

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Issue 06/04 Foreword

### **Foreword**

### **User Documentation**



### **WARNING**

Before installing and commissioning the inverter, you must read all safety instructions and warnings carefully including all the warning labels attached to the equipment. Make sure that the warning labels are kept in a legible condition and replace missing or damaged labels.

#### Information is also available from:

### **Regional Contacts**

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### **America**

Tel: +1 423 262 2522 Fax: +1 423 262 2589

Email: simatic.hotline@sea.siemens.com

### Asia

Tel: +86 1064 757 575 Fax: +86 1064 747 474

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# **Definitions and Warnings**



#### **DANGER**

indicates an immanently hazardous situation which, if not avoided, will result in death or serious injury.



#### **WARNING**

indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.



#### **CAUTION**

used with the safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury.

#### **CAUTION**

used without safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in a property damage.

### **NOTICE**

indicates a potential situation which, if not avoided, may result in an undesirable result or state.

### **NOTE**

For the purpose of this documentation, "Note" indicates important information relating to the product or highlights part of the documentation for special attention.

### **Qualified personnel**

For the purpose of this Instruction Manual and product labels, a "Qualified person" is someone who is familiar with the installation, mounting, start-up and operation of the equipment and the hazards involved.

He or she must have the following qualifications:

- 1. Trained and authorized to energize, de-energize, clear, ground and tag circuits and equipment in accordance with established safety procedures.
- 2. Trained in the proper care and use of protective equipment in accordance with established safety procedures.
- 3. Trained in rendering first aid.

### Use for intended purpose only

The equipment may be used only for the application stated in the manual and only in conjunction with devices and components recommended and authorized by Siemens.

Issue 06/04 Safety Instructions

# Safety Instructions

The following Warnings, Cautions and Notes are provided for your safety and as a means of preventing damage to the product or components in the machines connected. This section lists Warnings, Cautions and Notes, which apply generally when handling MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST Inverters, classified as General, Transport & Storage, Commissioning, Operation, Repair and Dismantling & Disposal.

**Specific Warnings, Cautions and Notes** that apply to particular activities are listed at the beginning of the relevant chapters and are repeated or supplemented at critical points throughout these chapters.

Please read the information carefully, since it is provided for your personal safety and will also help prolong the service life of your MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST Inverter and the equipment you connect to it.

### General



### **WARNING**

- This equipment contains dangerous voltages and controls potentially dangerous rotating mechanical parts. Non-compliance with **Warnings** or failure to follow the instructions contained in this manual can result in loss of life, severe personal injury or serious damage to property.
- Only suitable qualified personnel should work on this equipment, and only after becoming familiar with all safety notices, installation, operation and maintenance procedures contained in this manual. The successful and safe operation of this equipment is dependent upon its proper handling, installation, operation and maintenance.
- Risk of electric shock. The DC link capacitors in the inverter remain charged
  for five minutes after power has been removed. Extreme care must be taken
  NOT to touch the power connector terminals within this time period. Care
  must also be taken when disconnecting power from inverters connected via a
  power/mains bus as the DC link capacitors of the other inverters will create a
  risk of electrical shock from their own DC link capacitors.
- HP ratings are based on the Siemens 1LA motors and are given for guidance only; they do not necessarily comply with UL or NEMA HP ratings.
- Do not operate the equipment in direct sunlight.



### **CAUTION**

Children and the general public must be prevented from accessing or approaching the equipment!

This equipment may only be used for the purpose specified by the manufacturer. Unauthorized modifications and the use of spare parts and accessories that are not sold or recommended by the manufacturer of the equipment can cause fires, electric shocks and injuries.

Safety Instructions Issue 06/04

### **NOTICE**

Keep these operating instructions within easy reach of the equipment and make them available to all users

- Whenever measuring or testing has to be performed on live equipment, the regulations of Safety Code VBG 4.0 must be observed, in particular § 8 "Permissible Deviations when Working on Live Parts". Suitable electronic tools should be used.
- Before installing and commissioning, please read these safety instructions and warnings carefully and all the warning labels attached to the equipment. Make sure that the warning labels are kept in a legible condition and replace missing or damaged labels

### **Transport & Storage**



### **WARNING**

- Correct transport, storage, erection and mounting, as well as careful operation and maintenance are essential for proper and safe operation of the equipment.
- Use the lifting eyes provided if a motor has to be lifted. Do not lift machine sets by suspending the individual machines! Always check the capacity of the hoist before lifting any equipment.
- Do not paint over the black case finish of the inverter, as this will affect the unit's thermal performance.

### **CAUTION**

Protect the inverter against physical shocks and vibration during transport and storage. Also be sure to protect it against water (rainfall) and excessive temperatures.

Issue 06/04 Safety Instructions

### Commissioning



### **WARNING**

- Work on the device/system by unqualified personnel or failure to comply with warnings can result in severe personal injury or serious damage to material. Only suitably qualified personnel trained in the setup, installation, commissioning and operation of the product should carry out work on the device/system.
- This equipment must be grounded (IEC 536 Class 1, NEC and other applicable standards).
- If a Residual Current-operated protective Device (RCD) is to be used, it must be an RCD type B.
- Machines with a three-phase power supply, fitted with EMC filters, must not be connected to a supply via an ELCB (Earth Leakage Circuit-Breaker - see DIN VDE 0160, section 5.5.2 and EN50178 section 5.2.11.1).
- The following terminals can carry dangerous voltages even if the inverter is inoperative:
  - power supply terminals L1, L2, L3.
  - motor terminals U, V, W.
- The minimum discharge time is 5 minutes.
- This equipment must not be used as an 'Emergency Stop mechanism' (see EN 60204, 9.2.5.4).



• The inverter electronics contain static sensitive devices therefore precautions must be taken against electrostatic discharge (ESD) when handling the separated inverter assembly. These include not touching the internal surfaces of the inverter and ensuring that personnel are earthed while handling the unit. The terminal housing, including Filter and I/O modules, contain no sensitive components and therefore no special handling precautions are required when separated.

### **CAUTION**

The connection of power, motor and control cables to the inverter must be carried carefully to prevent inductive and capacitive interference from affecting the correct functioning of the inverter. For further information see the ECOFAST System Manual.

Issue 06/04 Safety Instructions

### Operation



### **WARNING**

- MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST operate at high voltages.
- When operating electrical devices, it is impossible to avoid applying hazardous voltages to certain parts of the equipment.
- Emergency Stop facilities according to EN 60204 IEC 204 (VDE 0113) must remain operative in all operating modes of the control equipment. Any disengagement of the Emergency Stop facility must not lead to uncontrolled or undefined restart.
- Wherever faults occurring in the control equipment can lead to substantial material damage or even grievous bodily injury (i.e. potentially dangerous faults), additional external precautions must be taken or facilities provided to ensure or enforce safe operation, even when a fault occurs (e.g. independent limit switches, mechanical interlocks, etc.).
- Certain parameter settings may cause the inverter to restart automatically after an input power failure.
- This equipment is capable of providing internal motor overload protection. Refer to P0610 (level 3) and P0335, I<sup>2</sup>T is ON by default. Motor overload protection can also be provided using an external PTC via a digital input.
- This equipment is suitable for use in a circuit capable of delivering not more than 100,000 symmetrical amperes (rms), for a maximum voltage of 480V when protected by an H or K Class fuse. (See Table 6-4).
- This equipment must not be used as an 'emergency stop mechanism' (see EN 60204, 9.2.5.4)
- When operating on an unsymmetrical power supply or in the event of faults, the earth leakage current may be permanently greater than 3.5 mA.

Issue 06/04 Safety Instructions

### Repair

### **WARNING**

Repairs on equipment may only be carried out by Service Center Drives
 authorized by Siemens or by authorized personnel who are thoroughly
 acquainted with all the warnings and operating procedures contained in this
 manual.

- Any defective parts or components must be replaced using parts contained in the relevant spare parts list.
- Disconnect the power supply before unplugging and opening the equipment for access. The user must wait for 5 minutes before accessing any terminals.

### **Dismantling & Disposal**

### **NOTE**

- Inverter packaging is re-usable. Retain the packaging for future use or return it to the manufacturer.
- Easy-to-release screw and snap connectors allow you to break the unit down into its component parts. You can then re-cycle these component parts, dispose of them in accordance with local requirements or return them to the manufacturer.

# **Table of Contents**

Foreword		5
Definitions	and Warnings	6
Safety Inst	tructions	7
Table of C	ontents	13
List of Illus	ions	15
List of Tab	les	16
1	Overview	17
1.1	MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST	18
1.2	Design Features	19
2	Installation	21
2.1	Installation after a Period of Storage	23
2.2	Ambient operating conditions	24
2.3	Mechanical Installation MICROMASTER 411 ECOFAST	26
2.4	Mechanical Installation COMBIMASTER 411 ECOFAST	31
2.5	ECOFAST Cable Connections	38
2.6	Installation ECOFAST PROFIBUS Module	39
3	Commissioning and Operation	43
3.1	Block Diagram	46
3.2	General Commissioning Information	47
3.3	Commissioning Overview with BOP or AOP	48
3.4	Commissioning with the Advanced Operator Panel (AOP)	51
3.5	Commissioning with PROFIBUS	52
3.6	Quick commissioning (P0010=1)	
3.7	General operation	62
4	System Parameters	65
4.1	Introduction to System Parameters	66
4.2	Parameter Structure	67
5	Troubleshooting	69
5.1	Troubleshooting with the Inverter LED	
5.2	Troubleshooting with the PROFIBUS LED	71
5.3	Troubleshooting with the Basic Operator Panel	
5.4	Faults and Alarms	73

6	Specifications	83
6.1	Technical Data	84
6.2	Case Size Rating Information	85
6.3	External Fuses and Circuit Breakers	87
7	ECOFAST Options	89
7.1	Options – Non-inverter Mounted	
7.2	Options – Inverter Mounted	90
8	Electro-Magnetic Compatibility (EMC)	93
8.1	Electro-Magnetic Compatibility (EMC)	94
Appendices	99	
A	Applicable Standards	99
В	List of Abbreviations.	

# List of Illusions

Figure 1-1	MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST	. 20
Figure 2-1	Forming	. 23
Figure 2-2	Derating with Temperature	. 24
Figure 2-3	Derating with Altitude	. 25
Figure 2-4	MICROMASTER 411 ECOFAST General Layout (with ECOFAST PROFIBUS Module)	. 27
Figure 2-5	Inverter power supply connector	. 28
Figure 2-6	Motor terminal connections	. 28
Figure 2-7	Dimensions (with ECOFAST PROFIBUS module)	. 29
Figure 2-8	Dimensions (with ECOFAST PROFIBUS module and EM module)	. 30
Figure 2-9	Dimensions (with ECOFAST PROFIBUS module and REM module)	. 30
Figure 2-10	COMBIMASTER 411 ECOFAST Connections	. 32
Figure 2-11	COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size B	. 33
Figure 2-12	COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size C	. 34
Figure 2-13	COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size B	. 35
Figure 2-14	COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size C	. 36
Figure 2-15	COMBIMASTER 411 ECOFAST – Dimensions Communication Modules	. 37
Figure 2-16	ECOFAST PROFIBUS Module Connections	. 39
Figure 2-17	PROFIBUS Data T-connector	. 40
Figure 2-18	ECOFAST PROFIBUS Address Identification Plug	. 41
Figure 2-19	Connecting the Hybrid Cables	. 42
Figure 2-20	PROFIBUS Termination	. 42
Figure 3-1	Block Diagram, MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST	. 46
Figure 3-2	Basic Operator Panel Controls	. 49
Figure 3-3	Changing parameters via the BOP	. 50
Figure 3-4	PROFIBUS Identification Plug	. 57
Figure 3-5	Typical Motor Rating Plate, Example	. 60
Figure 3-6	Connect BOP/AOP with the MICROMASTER 411	. 63
Figure 4-1	Parameter Structure with Filter (P0004)	. 67
Figure 7-1	ECOFAST PROFIBUS module	. 91

# List of Tables

Table 2-1	COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size B	. 33
Table 2-2	COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size C	. 34
Table 2-3	COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size B	. 35
Table 2-4	COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size C	. 36
Table 3-1	PROFIBUS External Inputs and Outputs	. 52
Table 3-2	PROFIBUS Parameters	. 52
Table 3-3	Parameters for flexible interconnection of process data	. 54
Table 3-4	Communication Board Functions	. 54
Table 3-5	Modification Source for Parameters via P0927	. 56
Table 5-1	Inverter LED Indication	. 70
Table 5-2	LED display on PROFIBUS communication Module	. 71
Table 6-1	COMBIMASTER 411 ECOFAST / MICROMASTER 411 ECOFAST Performance Ratings	
Table 6-2	Case Size B	. 85
Table 6-3	Case Size C	. 86
Table 6-4	External Fuses and Circuit Breakers	. 87
Table 7-1	Options – Non-inverter Mounted	. 90
Table 8-1	Environment - General Industrial	. 95
Table 8-2	Environment - Filtered Industrial	. 95
Table 8-3	Environment - Filtered for Residential, Commercial and Light Industry	. 96
Table 8-4	EMC Compliance Table	. 97
Table 8-5	MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST Measured Results	. 97

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Issue 06/04 1 Overview

# 1 Overview

This	Cha	oter	con	tain	S:

A summary of the major features of the MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST range.

1.1	MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST	18
1.2	Design Features	19

1 Overview Issue 06/04

# 1.1 MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST

The Siemens MICROMASTER 411 / COMBIMASTER 411 frequency inverters are used to control the speed of three phase AC induction motors.

MICROMASTER 411 offers an Inverter for adaptation to a compatible motor frame or for Wall Mounting and COMBIMASTER 411 provides for a ready to use Inverter/Motor combination unit.

In the ECOFAST variant all connections are realized as plugs. It has been designed to allow the quick and efficient installation and replacement of the inverters in time-critical applications.

MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST inverters are available in the following ranges:

MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST inverters are available in the following ranges:

- 370 W to 3.0 kW 380/480 VAC 3 Phase (Wall Mounted Variants) -MICROMASTER 411 ECOFAST.
- 370 W to 2.2 kW 380/480 VAC 3 Phase (Motor Mounted Variants) -COMBIMASTER 411 ECOFAST.

The inverters are microprocessor-controlled and use state-of-the-art Insulated Gate Bipolar Transistor (IGBT) technology. This makes them reliable and versatile. A special pulse-width modulation method with selectable Pulse frequency permits quiet motor operation.

Comprehensive protection is included as standard for both motor and inverter circuits.

With the commissioning software or an optional operator panel it is possible to select different modes of operation or to adapt the inverter to a certain drive drive task, via functional grouped parameters.

In the ECOFAST variant the communication interface is factory set as source for both, commands and setpoints

MICROMASTER 411 ECOFAST / COMBIMASTER 411 ECOFAST can be used in 'stand-alone' applications as well as being integrated into complete automation systems.

Issue 06/04 1 Overview

### 1.2 Design Features

### **Main Characteristics**

- · Easy installation
- Easy commissioning
- High starting torque with programmable starting boost
- Options for remote control:
  - Basic Operator Panel
  - Advanced Operator Panel
  - Serial interface (RS232)
- Factory default parameter settings pre-programmed for European settings, switchover to North American settings possible.
- Output frequency (and hence motor speed) can be controlled by one of the five methods:
  - Internal Speed Control Potentiometer
  - Analogue setpoint (voltage or current input)
  - Fixed frequencies via binary inputs
  - Serial interface
  - Communication Module (PROFIBUS / AS-Interface)
- · Programmable signal relay output incorporated
- Rugged EMC design
- Fast repeatable response time to control signals
- Comprehensive range of parameters enabling configuration for a wide range of applications
- Simple connection
- High switching frequencies for low-noise motor operation
- Detailed status information and integrated messaging functions
- Options
  - PC communications
  - ECOFAST PROFIBUS module
  - AS-Interface module
  - Basic Operator Panel (BOP),
  - Advanced Operator Panel (AOP)
  - EM Module (Electromechanical Brake Control Module)
  - REM Brake Module (Pulse Resistor and Electromechanical Brake Control Module)
- Integrated class A-filter (interference emission class A)

1 Overview Issue 06/04

### **Performance Characteristics**

- Flux Current Control (FCC) for improved dynamic response and motor control
- Fast Current Limitation (FCL) for trip-free operation
- Built-in DC injection brake
- COMPOUND braking to improve braking performance
- · Ramp function generator with programmable smoothing
- Control with Proportional-Integral control function (PI)
- Multi-point V/f characteristic

### **Protection characteristics**

- MICROMASTER 411 ECOFAST: Type of protection up to IP65
- COMBIMASTER 411 ECOFAST: Type of protection up to IP55 for the motor, IP65 for inverter and options
- Overvoltage / undervoltage protection
- Overtemperature protection for the inverter
- Short-circuit protection
- I2t thermal motor protection
- PTC for motor protection
- Stall prevention
- Parameter interlock

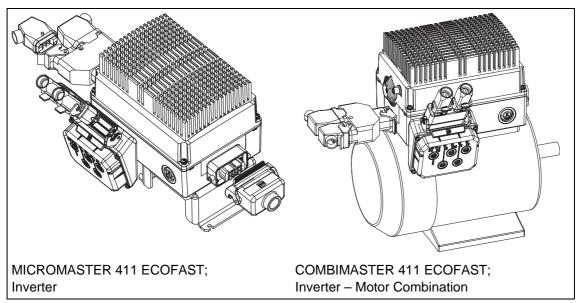


Figure 1-1 MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST

# 2 Installation

### This Chapter contains:

- General data relating to installation
- Inverter Dimensions
- Wiring guidelines to minimize the effects of EMI
- Details concerning electrical installation

2.1	Installation after a Period of Storage	23
2.2	Ambient operating conditions	24
2.3	Mechanical Installation MICROMASTER 411 ECOFAST	26
2.3.1	Installation Procedure	27
2.3.2	Dimensional Detail, MICROMASTER 411 ECOFAST	29
2.4	Mechanical Installation COMBIMASTER 411 ECOFAST	31
2.4.1	Installation Procedure	31
2.4.2	COMBIMASTER 411 ECOFAST Motor Design IM B 3	33
2.4.3	COMBIMASTER 411 ECOFAST Motor Design IM B 5	35
2.4.4	COMBIMASTER 411 ECOFAST Dimensions Communication Modules	37
2.5	ECOFAST Cable Connections	38
2.5.1	General	38
2.6	Installation ECOFAST PROFIBUS Module	39



### **WARNING**

- Work on the device/system by unqualified personnel or failure to comply with warnings can result in severe personal injury or serious damage to material. Only suitably qualified personnel trained in the setup, installation, commissioning and operation of the product should carry out work on the device/system.
- This equipment must be grounded (IEC 536 Class 1, NEC and other applicable standards).
- If a Residual Current-operated protective Device (RCD) is to be used, it must be an RCD type B.
- Machines with a three-phase power supply, fitted with EMC filters, must not be connected to a supply via an ELCB (Earth Leakage Circuit-Breaker EN50178 Section 5.2.11.1).
- The following terminals can carry dangerous voltages even if the inverter is inoperative:
  - power supply terminals L1, L2, L3.
  - motor terminals U, V, W.
- Risk of electric shock. The DC link capacitors in the inverter remain charged
  for five minutes after power has been removed. Extreme care must be taken
  NOT to touch the power connector terminals within this time period. Care
  must also be taken when disconnecting power from inverters connected via a
  power/mains bus as the DC link capacitors of the other inverters will create a
  risk of electrical shock from their own DC link capacitors.
- This equipment must not be used as an 'emergency stop mechanism' (see EN 60204, 9.2.5.4)
- The minimum size of the earth-bonding conductor must be equal to or greater than the cross-section of the power supply cables.
- When operating on an unsymmetrical power supply or in the event of faults, the earth leakage current may be permanently greater than 3.5 mA.

### **CAUTION**

The connection of power and motor cables to the inverter must be carried out carefully to prevent inductive and capacitive interference from affecting the correct functioning of the inverter. For further information see the ECOFAST System Manual.

## 2.1 Installation after a Period of Storage

Following a prolonged period of storage, you must reform the capacitors in the inverter. The requirements are listed below.

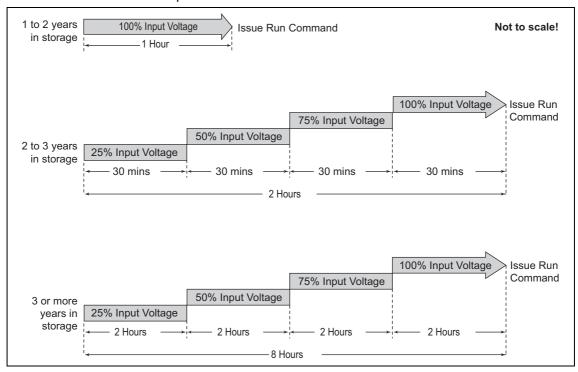


Figure 2-1 Forming

# 2.2 Ambient operating conditions

### **Temperature**

Operating temperature –10 °C to +40 °C

### **Humidity Range**

≤ 99 %, Non-condensing

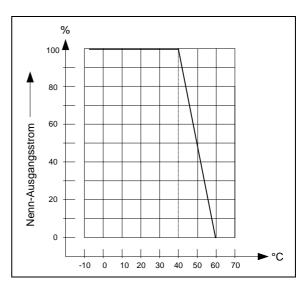


Figure 2-2 Derating with Temperature

### **Altitude**

If the inverter is to be installed at an altitude > 1000 m, derating will be required.

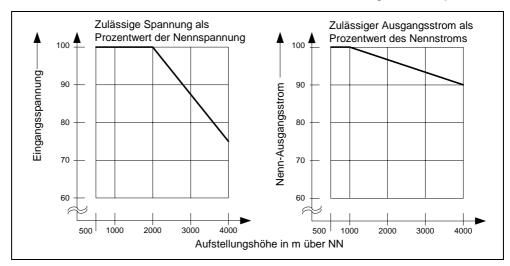


Figure 2-3 Derating with Altitude

### **Shock**

Do not drop the inverter or expose to sudden shock.

### **Electromagnetic Radiation**

Do not install the inverter near sources of electromagnetic radiation.

### **Overheating**

- MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST are cooled by natural convection.
- Mounting the inverter with the heatsink upside down is not allowed. Side mounting of the inverter is possible.
- Ensure that airflow around the inverter housing is not obstructed. Allow 100 mm clearance above and below the inverter.

### 2.3 Mechanical Installation MICROMASTER 411 ECOFAST



### **WARNING**

- THIS EQUIPMENT IS GROUNDED VIA THE POWER CABLE ON CONNECTION TO THE INVERTER.
- To ensure safe operation of the equipment, it must be installed and commissioned by qualified personnel in full compliance with the warnings laid down in these operating instructions.
- Take particular note of the general and regional installation and safety regulations regarding work on dangerous voltage installations (e.g. EN 50178), as well as the relevant regulations regarding the correct use of tools and personal protective gear.
- Risk of electric shock. The DC link capacitors in the inverter remain charged
  for five minutes after power has been removed. Extreme care must be taken
  NOT to touch the power connector terminals within this time period. Care
  must also be taken when disconnecting power from inverters connected via a
  power/mains bus as the DC link capacitors of the other inverters will create a
  risk of electrical shock from their own DC link capacitors.
- High Voltages. If the inverter is being installed/commissioned as part of an
  existing chain of inverters then extreme caution must be exercised as high
  voltages are present in the power cables of the preceding inverter in the chain.
- Correct Wiring. If the motor terminals are not connected correctly a potentially hazardous situation may occur resulting in severe damage to personnel and equipment.
- Star and Delta Configuration. The user must ensure that the motor cable is connected correctly to the motor terminals for either Star or Delta configuration.

### **Important NOTICE**

- The jumper terminals within the COMBIMASTER 411 & MICROMASTER 411 ECOFAST variant are fully functional, but no jumpers are connected.
- If further information on the jumpers are required, please refer to the standard COMBIMASTER 411 & MICROMASTER 411 Operating Instructions.

### 2.3.1 Installation Procedure

Physical dimensions and characteristics for the installation are given in Figure 27.

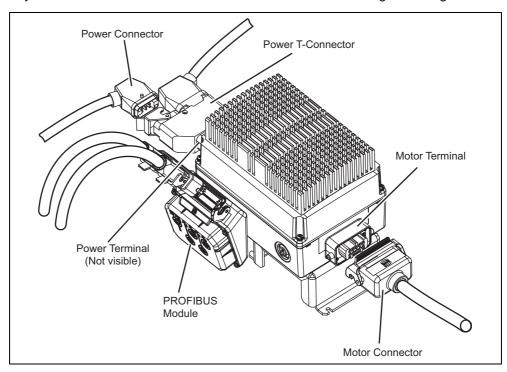


Figure 2-4 MICROMASTER 411 ECOFAST General Layout (with ECOFAST PROFIBUS Module)

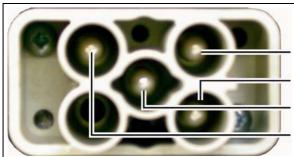
### **Power and Motor Connection**

### **NOTES**

- If the inverter being installed is part of a chain of several inverters then T-Connectors will be necessary for the correct installation of the inverter.
- The NSK Catalogue, section "System ECOFAST" provides all the necessary ordering information for ECOFAST cables and connectors.

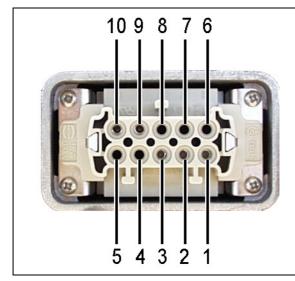
MICROMASTER 411 ECOFAST and COMBIMASTER 411 ECOFAST are delivered to the customer with all the ordered options pre-installed. Therefore the only installation that is required is to connect the relevant cables and connectors. Figure 2-4 shows the layout of all the connectors.

The inverters have a Harting HAN Q 4/2 connector for the Power supply (see Figure 2-5) and a Harting HAN 10 E Connector for the motor connection (see Figure 2-6).



	PIN	Assignment
-	1	L1
	2	L2
	3	L3
	4	PE

Figure 2-5 Inverter power supply connector



٦	Pin	Assignment Inverter	Assignment motor			
	1	Winding Terminal U1	Winding Terminal U1			
	2	Winding Terminal V1	Winding Terminal V1			
	3	Winding Terminal W1	Winding Terminal W1			
	4	Brake (reference potential)	Brake (reference potential)			
	5	Brake	Brake			
	6	-	Winding Terminal U2 Winding Terminal V2			
	7	-				
	8	-	Winding Terminal W2			
	9	Temperature Sensor (terminal A)	Temperature Sensor (terminal A)			
	10	Temperature Sensor (terminal B)	Temperature Sensor (terminal B)			

Figure 2-6 Motor terminal connections

There are prefabricated cables for both power supply and motor connection. For detailed information refer to the NSK Catalogue "System ECOFAST".

### **NOTES**

- Between Inverter and motor use a special EMC hybrid cable to fulfill EMC requirements.
- The MICROMASTER 411 ECOFAST has been internally configured to operate
  in STAR connection. If an ECOFAST motor is used, take care that the winding
  terminals at the motor ECOFAST power connector (Harting HAN 10E) are
  assigned as shown in Figure 2-6. The STAR connection is realized within the
  motor side connector of the cable between inverter and motor.

To ensure that the inverter is installed correctly, the following procedure must be performed (see Figure 2-4 for location of terminals and connectors):

- 1. Connect the power cable (HAN Q 4/2) to the power terminal on the inverter. See Figure 2-5
- 2. Connect the motor cable (HAN 10E) to the motor terminal on the inverter. See Figure 2-6
- 3. Secure the connectors.

### 2.3.2 Dimensional Detail, MICROMASTER 411 ECOFAST

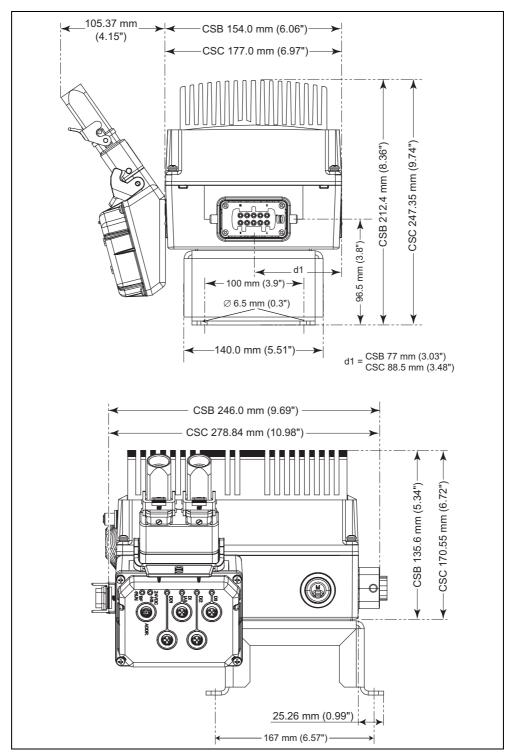


Figure 2-7 Dimensions (with ECOFAST PROFIBUS module)

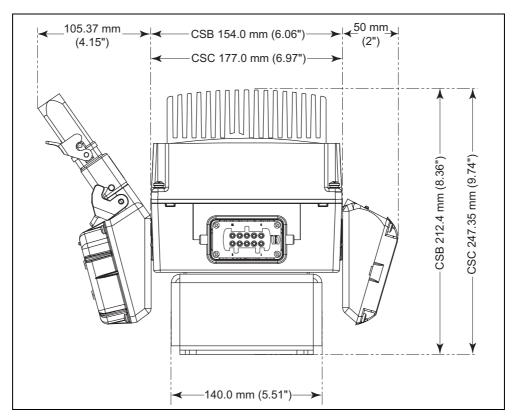


Figure 2-8 Dimensions (with ECOFAST PROFIBUS module and EM module)

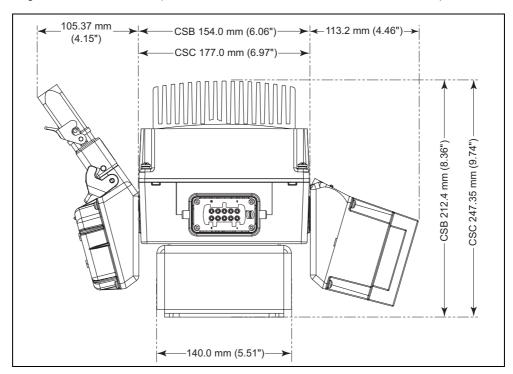


Figure 2-9 Dimensions (with ECOFAST PROFIBUS module and REM module)

### 2.4 Mechanical Installation COMBIMASTER 411 ECOFAST

### 2.4.1 Installation Procedure

Ensure that any lifting eyes are tightened down prior to moving the COMBIMASTER into position.

Use the lifting eyes provided if a motor has to be lifted. Always check the capacity of the hoist before lifting any equipment.



### **WARNING**

Do not attempt to lift the COMBIMASTER 411 ECOFAST using the inverter housing as this could result in severe damage to the inverter or motor and possibly severe personal injury.

Move the COMBIMASTER 411 ECOFAST into the required position and secure by inserting suitable foundation bolts through the motor feet (see Figure 2-11 to Figure 2-15). Allow adequate clearance of 100mm minimum around the unit to provide for air circulation.

Carry out the following checks prior to commissioning the COMBIMASTER 411 ECOFAST:

- 1. The rotor is correctly aligned and free to rotate without obstruction.
- 2. Transmission elements are adjusted correctly (e.g. belt tensioned) and suitable for the given operating conditions.
- 3. All electrical connections, mounting screws and connecting elements tightened and fitted correctly.
- 4. Protective conductors installed properly
- 5. Any auxiliary equipment that might be fitted (e.g. mechanical brake) is in working order.
- 6. Protection guards are installed around all moving and live parts and any relevant safety notices displayed.
- 7. Ensure all power supplies to the inverter and all the connectors are switched off before performing any connections.
- 8. Connect the Power T-Connector to the Power Terminal on the inverter (see Figure 2-10).
- 9. Connect the Power Connector to the Power T-Connector.
- 10. For the correct installation of the ECOFAST PROFIBUS module, (see Section 2.6).
- 11. Check all connections have been secured, using the clamps on the connectors.
- 12. Commissioning of the inverter can now be performed in accordance to the instructions given in Section 3.
- 13. For a description of the connectors and details of the pinouts see Section 2.3 and 2.6.

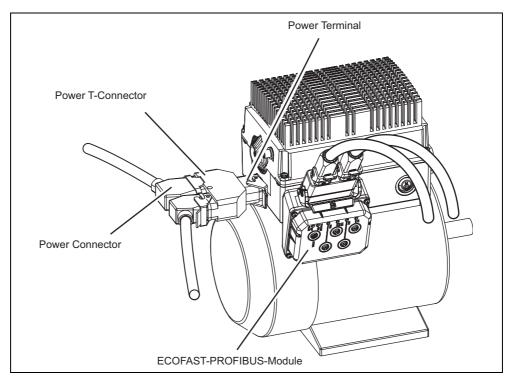


Figure 2-10 COMBIMASTER 411 ECOFAST Connections

### 2.4.2 COMBIMASTER 411 ECOFAST Motor Design IM B 3

### **Inverter Case Size B**

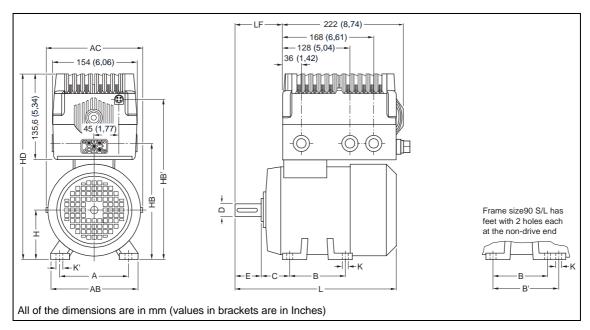


Figure 2-11 COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size B

Table 2-1 COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size B

Motor o	lata	Dime	nsions	symbol	to					
Frame size	Туре	IEC DIN	A b	AB f	AC g	B a	B' a'	C W <sub>1</sub>	D d	E I
71	1UA2 07		112 (4,41)	132 (5,20)	145 (5,71)	90 (3,54)	-	45 (1,77)	14 (0,55)	30 (1,18)
80	1UA2 08		125 (4,92)	150 (5,91)	163 (6,42)	100 (3,94)	-	50 (1,97)	19 (0,75)	40 (1,57)
90 S 90 L	1UA2 090 1UA2 096-4		140 (5,51)	165 (6,50)	180 (7,09)	100 (3,94)	125 (4,92)	56 (2,20)	24 (0,94)	50 (1,97)
Frame size	Туре	IEC DIN	H h	HB v	HB' v'	HD p	K s	K' s <sub>1</sub>	L k	LF q
71	1UA2 07		71 (2,80)	172 (6,77)	234,6 (9,24)	278,6 (10,97)	7 (0,28)	10 (0,39)	240 (9,45)	54 (2,13)
80	1UA2 08		80 (3,15)	190 (7,48)	252,6 (9,94)	296,6 (11,68)	9,5 (0,37)	13,5 (0,53)	273,5 (10,77)	64 (2,52)
90 S 90 L	1UA2 090 1UA2 096-4		90 (3,54)	208 (8,19)	270,6 (10,65)	314,6 (12,39)	10 (0,39)	14 (0,55)	331 (13,03)	89,5 (3,52)

### **Inverter Case Size C**

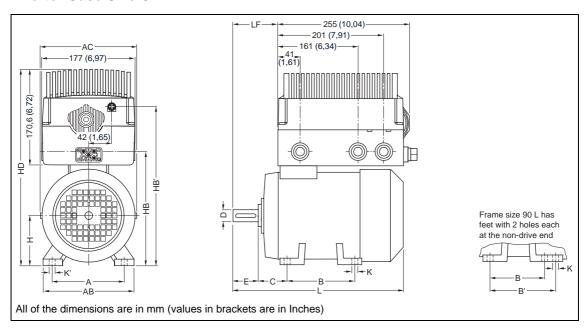


Figure 2-12 COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size C

Table 2-2 COMBIMASTER 411 ECOFAST – Motor Design IM B 3 – Case Size C

Motor data		Dime	Dimensions symbol to								
Frame size	Туре	IEC DIN	A b	AB f	AC g	B a	B' a'	C W <sub>1</sub>	D d	E I	
90L	1UA2 096-2		140	165	180	100	125	56	24	50	
			(5,51)	(6,50)	(7,09)	(3,94)	(4,92)	(2,20)	(0,94)	(1,97)	
100L	1UA2 106		160	196	203	140	-	63	28	60	
			(6,30)	(7,72)	(7,99)	(5,51)	-	(2,48)	(1,10)	(2,36)	
Frame size	Туре	IEC DIN	H h	HB v	HB' v'	HD p	K s	K' s <sub>1</sub>	L k	LF q	
90L	1UA2 096-2		90	208	280	349,5	10	14	331	88,5	
			(3,54)	(8,19)	(11,02)	(13,76)	(0,39)	(0,55)	(13,07)	(3,48)	
100L	1UA2 106		100	225	300	370	12	16	372	98	
			(3,94)	(8,86)	(11,81)	(14,57)	(0,47)	(0,63)	(14,69)	(3,86)	

### 2.4.3 COMBIMASTER 411 ECOFAST Motor Design IM B 5

### **Inverter Case Size B**

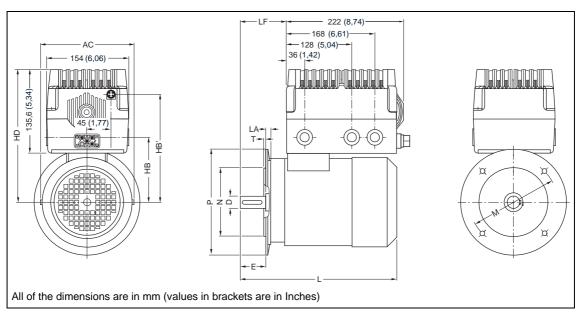


Figure 2-13 COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size B

Table 2-3 COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size B

Motor data		Dimensions symbol to								
Frame size	Туре	IEC DIN	AC g	D d	E I	HB v	HB' V₁	HD p	L k	
71	1UA2 07		145	14	30	101	163,6	207,6	240	
			(5,71)	(0,55)	(1,18)	(3,98)	(6,44)	(8,17)	(9,45)	
80	1UA2 08		163	19	40	110	172,6	216,6	273,5	
			(6,42)	(0,75)	(1,57)	(4,33)	(6,80)	(8,53)	(10,77)	
90 S	1UA2 090		180	24	50	118	180,6	224,6	331	
90 L	1UA2 096-4		(7,09)	(0,94)	(1,97)	(4,65)	(7,11)	(8,84)	(13,03)	
Frame size	Туре	IEC DIN	LA c <sub>1</sub>	LF q	M e <sub>1</sub>	N b <sub>1</sub>	P a <sub>1</sub>	S S <sub>2</sub>	T f <sub>1</sub>	
71	1UA2 07		9	54	130	110	160	10	3,5	
			(0,35)	(2,13)	(5,12)	(4,33)	(6,30)	(0,39)	(0,14)	
80	1UA2 08		10	64	165	130	200	12	3,5	
			(0,39)	(2,52)	(6,50)	(5,12)	(7,87)	(0,47)	(0,14)	
90 S	1UA2 090		10	89,5	165	130	200	12	3,5	
90 L	1UA2 096-4		(0,39)	(3,52)	(6,50)	(5,12)	(7,87)	(0,47)	(0,14)	

### **Inverter Case Size C**

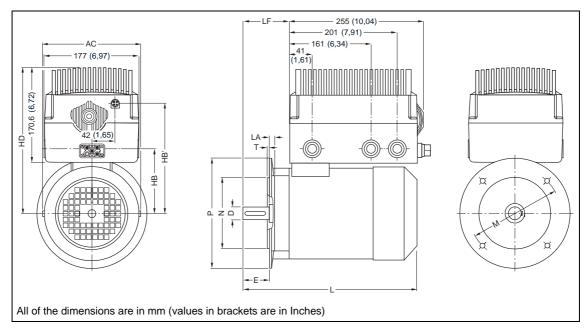


Figure 2-14 COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size C

Table 2-4 COMBIMASTER 411 ECOFAST – Motor Design IM B 5 – Case Size C

Motor data		Dimensions symbol to									
Frame size	Туре	IEC DIN	AC g	D d	E I	HB v	HB' V <sub>1</sub>	HD p	L k		
90L	1UA2 096-2		180 (7,09)	24 (0,94)	50 (1,97)	118 (4,65)	190 (7,48)	259,5 (10,22)	331 (13,03)		
100L	1UA2 106		203 (7,99)	28 (1,10)	60 (2,36)	125 (4,92)	200 (7,87)	270 (10,63)	372 (14,65)		
		I									
Frame size	Туре	IEC DIN	LA c <sub>1</sub>	LF q	M e <sub>1</sub>	N b <sub>1</sub>	P a <sub>1</sub>	S s <sub>2</sub>	T f <sub>1</sub>		
90L	1UA2 096-2		10 (0,39)	88,5 (3,48)	165 (6,50)	130 (5,12)	200 (7,87)	12 (0,47)	3,5 (0,14)		
100L	1UA2 106		11 (0,43)	64 (2,52)	215 (8,46)	180 (7,09)	250 (9,84)	14,5 (0,57)	4 (0,16)		

Issue 06/04 2 Installation

## 2.4.4 COMBIMASTER 411 ECOFAST Dimensions Communication Modules

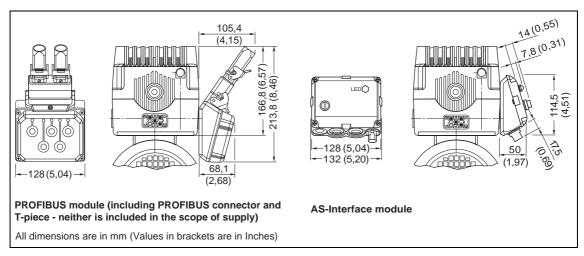


Figure 2-15 COMBIMASTER 411 ECOFAST – Dimensions Communication Modules

2 Installation Issue 06/04

#### 2.5 ECOFAST Cable Connections



#### **WARNING**

- THIS EQUIPMENT IS GROUNDED VIA THE CONNECTED POWER CABLE.
- To ensure the safe operation of the equipment, it must be installed and commissioned by qualified personnel in full compliance with the warnings laid down in these operating instructions.
- Take particular note of the general and regional installation and safety regulations regarding work on dangerous voltage installations (e.g. EN 50178), as well as the relevant regulations regarding the correct use of tools and personal protective gear.
- Risk of electric shock. The DC link capacitors in the inverter remain charged
  for five minutes after power has been removed. Extreme care must be taken
  NOT to touch the power connector terminals within this time period. Care
  must also be taken when disconnecting power from inverters connected via a
  power/mains bus as the DC link capacitors of the other inverters will create a
  risk of electrical shock from their own DC link capacitors.

#### 2.5.1 General



#### **WARNING**

If the inverter is not grounded correctly, extremely dangerous conditions may arise within the inverter which could prove potentially fatal.

#### **Operation with Residual Current Device (RCD)**

If an RCD (also referred to as ELCB or RCCB) is fitted, the MICROMASTER 411 ECOFAST Inverters will operate without nuisance tripping, provided that:

- A type B RCD is used.
- The trip limit of the RCD is 300mA.
- The neutral of the supply is grounded.
- Only one inverter is supplied from each RCD.

Issue 06/04 2 Installation

#### 2.6 Installation ECOFAST PROFIBUS Module

The ECOFAST PROFIBUS Module has been designed to allow the easy connection to external inputs and outputs via terminal connections on the external casing of the module housing. Figure 2-16 shows the location and purpose of all the external connections.

The connectors are a standard M12 connector which are protected when not in use by a screw cap.

The communications cables are connected to the ECOFAST PROFIBUS Module housing as shown in Figure 2-17, Figure 2-19 and Figure 2-20.

For further details of the functionality and operation of the ECOFAST PROFIBUS Module, please refer to the COMBIMASTER 411 & MICROMASTER 411 ECOFAST PROFIBUS Module Operating Instructions, Order Number 6SE6400-5AV00-0BP0. This document is provided on the CD-ROM supplied with the inverter.

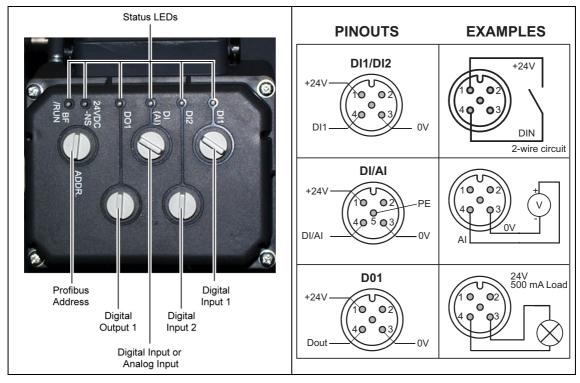


Figure 2-16 ECOFAST PROFIBUS Module Connections

#### **External Connectors LEDs**

The individual external connectors on the ECOFAST PROFIBUS module have their own status LEDs. These indicate the working status of the connection. Green indicates the connections is working. If the connection is not working or is not connected the LED will not be illuminated.

2 Installation Issue 06/04

#### **NOTES**

Inputs and output are supplied with DC 24 V via the ECOFAST System.

#### **ECOFAST PROFIBUS Connections**

The ECOFAST PROFIBUS Module is the main communications device for the ECOFAST MICROMASTER 411.

To ensure the correct functioning of the ECOFAST PROFIBUS Module the following installation procedure should be performed:

#### **CAUTION**

It is essential for the correct operation of the ECOFAST PROFIBUS Module that the 24 V external power supply is provided via the Hybrid Fieldbus cable, through the Data-T connector to the ECOFAST PROFIBUS Module.

- Connect the Data T-connector to the PROFIBUS data terminal. See Figure 2-17.
- 2. Secure the Data T-connector into position with the locking latch.
- Configure the PROFIBUS address using the Address Identification Plug. See Figure 2-18 (order number: 6ES7-194-1KB00-0XA0)

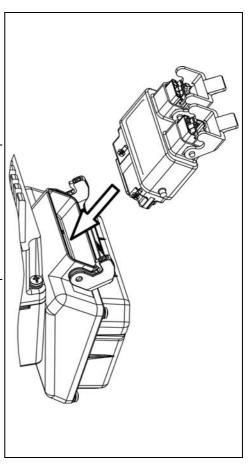


Figure 2-17 PROFIBUS Data T-connector

Issue 06/04 2 Installation

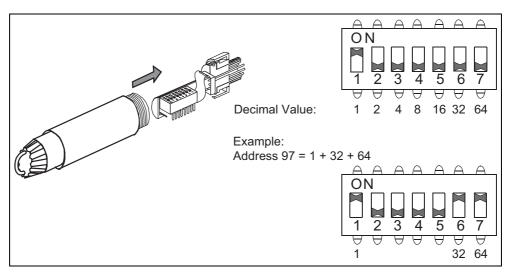


Figure 2-18 ECOFAST PROFIBUS Address Identification Plug

- 4. Screw the Address Identification Plug into the ECOFAST PROFIBUS module address socket, shown in Figure 2-16.
- 5. Connect the Hybrid Fieldbus cable into the Data T-connector. See Figure 2-19.
- With the connection of the Hybrid Fieldbus cable, the 24 V external power supply will provide power to the unit and the Address Identification Plug will be recognized by the inverter software.

#### **CAUTION**

It is the function of providing the power to the ECOFAST PROFIBUS Module via the Hybrid Fieldbus cable that allows the inverter to recognize the ECOFAST PROFIBUS Module and read the address set by the Identification Plug. If the address is set after power has been provided to the ECOFAST PROFIBUS Module, then the power supply to the ECOFAST PROFIBUS Module must be disconnected and the reconnected for the address to be read into the inverter.

2 Installation Issue 06/04

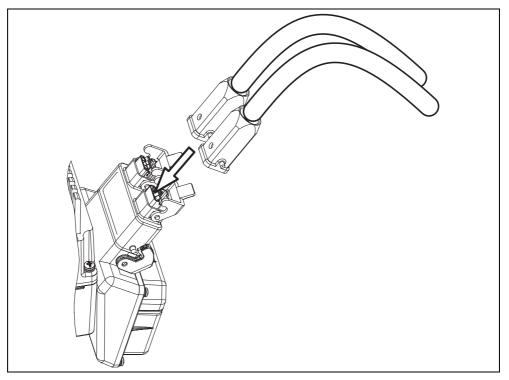


Figure 2-19 Connecting the Hybrid Cables

- 7. Secure the hybrid cables into position with the locking latches.
- 8. If the ECOFAST PROFIBUS module is the last in the chain of modules, then connect one Hybrid Fieldbus cable and one bus terminator connector in the remaining data socket. See Figure 2-20.
- If the installation is successful, the 24 VDC and BF/RUN LEDs will show a steady green colour. For a full description of LED states see Section 5.2.
- 10.The GSD file for the PROFIBUS is on the Document CD-ROM or can be downloaded from the appropriate Siemens website.

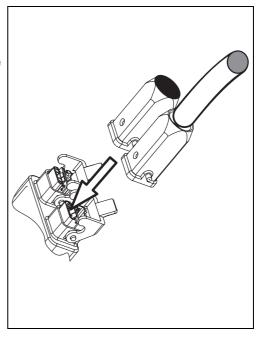


Figure 2-20 PROFIBUS Termination

## 3 Commissioning and Operation

### This Chapter contains:

- A schematic diagram of the MICROMASTER 411 / COMBIMASTER 411
- An overview of the commissioning options and the display and operator panels
- An overview of quick commissioning of the MICROMASTER 411 / COMBIMASTER 411

3.1	Block Diagram	46
3.2	General Commissioning Information	47
3.2.1	Default setup	47
3.3	Commissioning Overview with BOP or AOP	48
3.3.1	Commissioning with the Basic Operator Panel (BOP)	48
3.4	Commissioning with the Advanced Operator Panel (AOP)	51
3.5	Commissioning with PROFIBUS	52
3.5.1	PROFIBUS External Inputs and Outputs	52
3.5.2	Configuration of the PROFIBUS	52
3.5.2.1	PROFIBUS Parameters	52
3.5.2.2	Setting the PROFIBUS Address	56
3.6	Quick commissioning (P0010=1)	58
3.6.1	Reset to Factory default	61
3.7	General operation	62
3.7.1	Modes of Operation	62
3.7.2	Stopping the Motor	64
3.7.3	If the Motor does not start up	64
371	If a fault occurs	64



#### **WARNING**

- COMBIMASTER411/MICROMASTER 411 ECOFAST operates at high voltages.
- When operating electrical devices, it is impossible to avoid applying hazardous voltages to certain parts of the equipment.
- Emergency Stop facilities according to EN 60204 IEC 204 (VDE 0113) must continue to function in all operating modes of the control equipment. Any disengagement of the Emergency Stop facility must not lead to uncontrolled or undefined restart.
- Wherever faults occurring in the control equipment may lead to substantial
  material damage, or even grievous bodily injury, (i.e. potentially dangerous
  faults), additional external precautions must be taken or facilities provided to
  ensure or enforce safe operation, even when a fault occurs (e.g. independent
  limit switches, mechanical interlocks, etc.).
- Certain parameter settings may cause the inverter to restart automatically after an input power failure.
- This equipment is capable of providing internal motor overload protection. Refer to P0610 (level 3) and P0335, I2T is ON by default. Motor overload protection can also be provided using an external PTC via a digital input.
- This equipment is suitable for use in a circuit capable of delivering not more than 100,000 symmetrical amperes (rms), for a maximum voltage of 460V when protected by an H or K Class fuse (see Table on Page 79).
- This equipment must not be used as an 'emergency stop mechanism' (see EN 60204, 9.2.5.4).



#### **CAUTION**

Only qualified personnel may enter settings in the control panels. Particular attention must be paid to safety precautions and warnings at all times.

The COMBIMASTER 411 ECOFAST & MICROMASTER 411 ECOFAST is supplied with default parameter settings that cover the following requirements:

- The motor rating data, voltage, current and frequency are all compatible with the inverter data.
- Linear V/f motor speed, controlled via communications network (PROFIBUS or AS Interface).
- The maximum output frequency for the COMBIMASTER 411 ECOFAST (1LA7 motor) is 100 Hz (2 pole; 6000 rpm) and 140 Hz (4 pole: 4200 rpm) controllable using commands provided via the communications network (PROFIBUS or AS Interface).
- The maximum output frequency for the MICROMASTER 411 ECOFAST is 650 Hz, controllable using commands provided via the communications network (PROFIBUS or AS Interface).
- Ramp-up time / Ramp-down time = 10 s.

If more complex application settings are required, please refer to the parameter listing.

Parameters can be changed either locally or remotely:

- Locally: by using a Basic Operator Panel (BOP) or an Advanced Operator Panel (AOP). Both are optional devices that must be ordered separately.
- Remotely: by using the communications network or a PC-based commissioning tool connected to the serial interface of the inverter.

## 3.1 Block Diagram

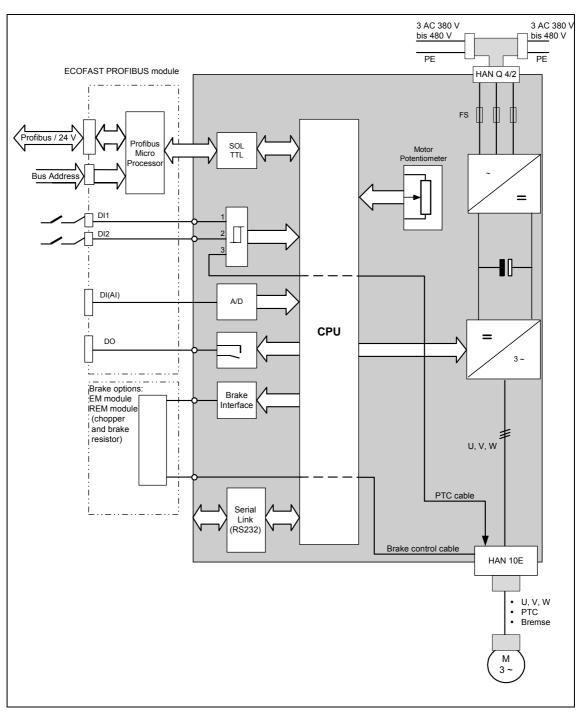


Figure 3-1 Block Diagram, MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST

#### **NOTE**

For details of the parameters regarding the analogue and digital input/outputs see Table 3-1.

## 3.2 General Commissioning Information

The ECOFAST inverters are set up to operate as default under the control of an external bus communications network (PROFIBUS or AS-Interface).

Parameters can be changed either locally or remotely:

- Locally: by using a Basic Operator Panel (BOP) or an Advanced Operator Panel (AOP). Both are optional devices that must be ordered separately.
- Remotely: by using the communications network or a PC-based commissioning tool connected to the serial interface of the inverter.



#### **WARNING**

The inverter does not have a power supply switch and is therefore live when the power supply is connected.

## 3.2.1 Default setup



#### **WARNING**

A factory reset will set the command source to DIN 1 (On/(OFF1). Therefore make sure that after a factory reset, the motor cannot start unintentionally from an command via DIN1 (e.g. by a photocell or a BERO).

If a factory reset has been done (P0010 = 30 and P0970 = 1), the command source and the frequency setpoint source are set to "Terminals" and "Analog setpoint" respectively.

To re-establish the ECOFAST default settings, set the following:

- P0700 = 6 (Command source via communications network)
- P1000 = 6 (Frequency setpoint source via communications network)

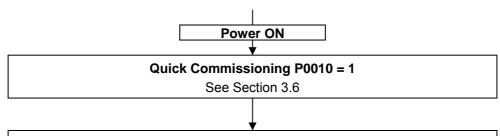
#### **IMPORTANT NOTICE**

- The jumper terminals within the MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST variant are fully functional, but no jumpers are connected.
- If further information on the jumpers are required, please refer to the standard COMBIMASTER 411 & MICROMASTER 411 Operating Instructions.

## 3.3 Commissioning Overview with BOP or AOP

#### **Prerequisites:**

Mechanical and electrical Installation is completed.



#### Further Commissioning via P0004 and P0003

An overview of the parameter structure is given in Section 4.2. For a detailed description of parameters, see the Parameter List.

#### NOTE

We recommend the commissioning according this scheme. Nevertheless an expert user is allowed to do the commissioning without the filter functions of P0004.

## 3.3.1 Commissioning with the Basic Operator Panel (BOP)



The Basic Operator Panel (BOP), which is available as an optional accessory, provides the user with access to the inverter parameters and enables you to customize the settings of your COMBIMASTER 411 ECOFAST & MICROMASTER 411 ECOFAST. The BOP can be used to configure several inverters. There is no need to purchase a separate BOP for each inverter. The BOP is mounted in an Operator Panel Mounting Kit, see Operating Instructions MICROMASTER 411 & COMBIMASTER 411, Section 8.

It should be noted that the BOP motor control functions are disabled by default. To control the motor via the BOP, parameter P0700 should be set to 1.

#### NOTE

If the BOP is set as the command source (P0700=1) and it is removed from the inverter during normal operation, the inverter will stop and the motor will coast to a standstill.

## **Buttons on the Basic Operator Panel**

Panel/Button	Function	Effects
r0000	Indicates Status	The LCD displays the settings currently used by the inverter.
	Start motor	Pressing the button starts the inverter. This button is disabled by default. To enable this button set P0700 = 1.
0	Stop motor	OFF1 Pressing the button causes the motor to come to a standstill at the selected ramp down rate. Disabled by default; to enable set P0700 = 1.  OFF2 Pressing the button twice (or once long) causes the motor to coast to a standstill. This function is always enabled.
	Change direction	Press this button to change the direction of rotation of the motor. Reverse is indicated by a minus (-) sign or a flashing decimal point. Disabled by default, to enable set P0700 = 1.
jog	Jog motor	Pressing this button while the inverter has no output causes the motor to start and run at the preset jog frequency. The motor stops when the button is released. Pressing this button when the motor is running has no effect.
Fn	Functions	This button can be used to view additional information.  Pressing and holding the button for 2 seconds from any parameter during operation, shows the following:  1. DC link voltage (indicated by d – units V).  2. Output current. (A)  3. Output frequency (Hz)  4. Output voltage (indicated by o – units V).  5. The value selected in P0005 (If P0005 is set to show any of the above (1 to 4) then this will not be shown again).  Additional presses will toggle around the above displays.  Jump Function  From any parameter (rXXXX or PXXXX) a short press of the Fn button will immediately jump to r0000, you can then change another parameter, if required. Upon returning to r0000, pressing the Fn button will return you to your starting point.  Quit  In case of a fault or alarm the Fn button resets the fault or alarm message on the operator panel display.
P	Access parameters	Pressing this button allows access to the parameters.
	Increase value	Pressing this button increases the displayed value.
	Decrease value	Pressing this button decreases the displayed value.

Figure 3-2 Basic Operator Panel Controls

#### Changing parameters with the BOP

The procedure for changing the value of parameter P0004 is described below. Modifying the value of an indexed parameter is illustrated using the example of P0719. Follow exactly the same procedure to alter other parameters that you wish to set via the BOP.

#### Changing P0004 – parameter filter function

Step		R	esult on displa	y
1	Press to access parameters		r0000	
2	Press until P0004 is displayed		P0004	
3	Press to access the parameter value level		0000	
4	Press or to the required value		0007	
5	Press to confirm and store the value		P0004	
_				

## 6 Only the command parameters are visible to the user.

## Changing P0719 an indexed parameter

## Selection of command/setpoint source

	Step	Re	esult on displa	ay
1	Press to access parameters		-0000	
2	Press until P0719 is displayed		P0719	
3	Press to access the parameter value level		10000	
4	Press to display current set value		0000	
5	Press or to the required value		0012	
6	Press to confirm and store the value		P0719	
7	Press until r0000 is displayed		-0000	
8	Press to return the display to the standard drive display (as defined by the customer)			

Figure 3-3 Changing parameters via the BOP

#### **NOTE**

In some cases - when changing parameter values - the display on the BOP shows

— busy

This means the inverter is busy with tasks of higher priority.

#### Changing single digits in Parameter values

For changing the parameter value rapidly, the single digits of the display can be changed by performing the following actions:

Ensure you are in the parameter value changing level (see "Changing parameters with BOP").

- 1. Press (function button), which causes the right hand digit to blink.
- 2. Change the value of this digit by pressing ( ) / ( ).
- 3. Press (function button) again causes the next digit to blink.
- 4. Perform steps 2 to 4 until the required value is displayed.
- 5. Press the to leave the parameter value changing level.

#### **NOTE**

The function button may also be used to acknowledge a fault condition

# 3.4 Commissioning with the Advanced Operator Panel (AOP)



The Advanced Operator Panel (AOP) is available as an option. Its advanced features include the following:

- Multilingual clear text display
- Upload/download facility for multiple parameter sets
- Programmable via PC
- Multidrop capability to drive up to 30 MICROMASTER 4's

Please refer to the AOP Manual for details or contact your local Siemens sales office for assistance.

## 3.5 Commissioning with PROFIBUS

## 3.5.1 PROFIBUS External Inputs and Outputs

The ECOFAST inverters are set up to operate as default under the control of an external bus communications network (PROFIBUS or AS-Interface).

The ECOFAST PROFIBUS module has 4 external input/output connections. They are not active by default. To activate, set the parameters given in Table 3-1 below.

Table 3-1 PROFIBUS External Inputs and Outputs

Input/Output	Parameter	Remarks
Digital Input 1 (DI1)	P0701	
Digital Input 2 (DI2)	P0702	
Digital Input (DI) or Analog Input 1 (AI)	P0704	To enable as Analog Input set: P0704 = 0 P1000 = 2
Digital Output (DO1)	P0731	
PTC	P0703	If a PTC is connected set P0703 = 29, to activate temperature monitoring

The pinouts of the input and output connectors (with examples) are shown in Figure 2 13.

## 3.5.2 Configuration of the PROFIBUS

### 3.5.2.1 PROFIBUS Parameters

The parameters shown in Table 3-2 must be set to correctly configure the ECOFAST PROFIBUS module:

Table 3-2 PROFIBUS Parameters

Parameter	Content
P0918	PROFIBUS address
P0719	Process data master control
P0700	Fast selection command source
P1000	Fast selection frequency setpoint
r2050 (Read-only)	Process data setpoint source (BICO)
P2051	Process data actual values (BICO)
P2041	Communication board functions
P2040	Process data telegram failure time
P0927	Modification source for parameters
r2054 (Read-only)	Communication board diagnostics (see Section 5.2)

#### P0918 - PROFIBUS address

If address 0 is set on the option interface board (default setting), then the PROFIBUS address can be changed using P0918.

Valid settings are 1 to 125 (default = 3).

Once a valid PROFIBUS address has been set via the address socket, P0918 can not be changed while the identification plug is fitted. In this case, the parameter displays the socket set PROFIBUS address.

The "Reset inverter parameters to factory setting" function also resets the PROFIBUS address to 3 if it has been set originally via P0918.

#### P0719 - Process Data Master Control

For simple applications, P0719 can be set to 66 to select the setpoint source. Control Word 1 and the Master Setpoint are then accepted by the ECOFAST PROFIBUS module.

Status Word 1 and the actual main value are output via the ECOFAST PROFIBUS module regardless of the setting in P0719.

P0719 has priority over P0700 and P1000.

#### P0700 and P1000 - Fast Selection

The control word and setpoint sources can be selected quickly in P0700 (select command source) and P1000 (select frequency setpoint) respectively.

P0719 must be set to 0 when BICO technology is used with P700 and P1000.

#### r2050 and P2051 - BICO

Much greater flexibility is afforded by the interconnection of process data using binectors/connectors, see description "Use of binectors and connectors" in the reference manual.

Detailed connection of setpoints and actual values to and from the ECOFAST PROFIBUS module is parameterized in r2050 and P2051.

The Table 3-3 shows the parameters specific to the ECOFAST PROFIBUS module relating to the connection of process data:

Table 3-3 Parameters for flexible interconnection of process data

Telegram:	PZD1 STW/ZSW	PZD2 HSW/HIW	PZD3	PZD4
Link values for setpoints master $\rightarrow$ inverter	r2050.00	r2050.01	r2050.02	r2050.03
Link parameters for actual values inverter → master	P2051.00	P2051.01	P2051.02	P2051.03
PZD: Process data ZSW: Status word HIW: Main actual STW: Control word HSW: Main setpoint		tual value		

#### **NOTE**

r2050 also acts as a display parameter via which the setpoints received by the ECOFAST PROFIBUS module can be checked.

#### **P2041 – Communication Board Functions**

A number of advanced property settings for the ECOFAST PROFIBUS module can be made in the indexed parameter P2041.

However, for most applications the defaults settings are adequate (value = 0). Table 3-4 below shows the property setting options.

Table 3-4 Communication Board Functions

Parameter	Meaning	Value range	
P2041.00	PPO type is specified by slave: Some (rare!) PROFIBUS masters require a configuration specified by the slave. This option can be programmed in this parameter.	0: PPO1 1: PPO1 3: PPO3	
P2041.01	OP parameter in EEPROM: Modifications to parameter settings via SIMATIC HMI are stored permanently in the EEPROM or as volatile data in the RAM.	0: Permanent (EEPROM) 1: Volatile (RAM)	
P2041.02	Internode communication failure: Reaction of communication board (as subscriber) after failure of a publisher	O: Generate alarm A704 and abort setpoint transmission to inverter (may activate fault 70)  1: Generate alarm A704 only	
P2041.03	Select displayed diagnostics screen.	Standard diagnostics     Special diagnostics (for SIEMENS internal use only)	

#### **Process data monitoring**

Two parameters determine how process data is monitored:

- Threshold monitoring on the ECOFAST PROFIBUS module(standard slave function according to PROFIBUS)
- Monitoring of the telegram failure time in the inverter with parameter "P2040"

The threshold monitoring function on the ECOFAST PROFIBUS module is normally activated. It can be deactivated via the PROFIBUS master configuring tool.

#### **NOTE**

The threshold monitoring function should not be deactivated!

#### P2040 - Telegram Failure Time

Parameter P2040 is set to determine whether setpoint transmission via PROFIBUS should be monitored by the inverter.

- P2040 = 0 means: No monitoring
- P2040 > 0 means: The value of "P2040" is the telegram failure time in milliseconds. (The default setting of the parameter is a value of >0!)

Fault 0070 is activated if no new setpoints are received by the ECOFAST PROFIBUS module within the telegram failure period.

#### **Important NOTE**

Shutdown on faults only take place if both monitoring functions are activated!

When the ECOFAST PROFIBUS module is in operation, P2040 should also be set to a value of > 0. The process data monitoring function is thus activated/deactivated solely via the PROFIBUS threshold monitor. Monitoring time then corresponds to the threshold monitoring time setting + the setting in P2040.

#### **NOTE**

Process data whose complete control word (PZD1) is set to zero are not transferred from the ECOFAST PROFIBUS module to the inverter.

Result: Alarm A703 and possibly fault 70.

#### **P0927 – Modification Source for Parameters**

This parameter can be set to define the sources of parameter modifications.

Table 3-5 Modification Source for Parameters via P0927

Bit 0	PROFIBUS-DP	0: No
Dit 0		1: Yes
Bit 1	BOP	0: No
DIL I	BOP	1: Yes
Bit 2	PC-inverter assembly set (USS on the BOP interface)	0: No
DIL Z	PC-Inverter assembly set (055 on the BOP interface)	1: Yes
Bit 3	Local RS-485 interface (terminal 14/15 and USS)	0: No
		1: Yes

The default setting for all bits is 1, i.e. parameters can be modified from all sources.

## 3.5.2.2 Setting the PROFIBUS Address

The ECOFAST PROFIBUS module is delivered with the default address value of 3. The address can be set using either the PROFIBUS Identification Plug or by parameter P0918 using an appropriate Operator Panel.

The Identification Plug is available as an accessory (order number: 6ES7-194-1KB00-0XA0).

#### **Setting the Address using Identification Plug**

- 1. Unscrew the cover of the identification plug. See Figure 3-4 below.
- 2. Carefully pull out the DIP Switch.
- 3. Using a small screwdriver, set the required PROFIBUS address (1 to 126) on the DIP Switch.
- 4. Push The DIP Switch back into the cover.
- 5. Tighten the cover.
- 6. Ensure that the power to the PROFIBUS module and the inverter is OFF.

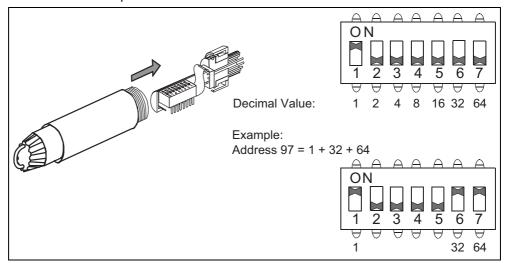


Figure 3-4 PROFIBUS Identification Plug

- 7. Screw the identification plug into the address port of the ECOFAST PROFIBUS module. See Figure 2-16 on page 39.
- 8. Cycle the power of the inverter. After the power cycle is complete, the address will have been read and stored from the Identification Plug into the inverter software.

#### **NOTES**

The Identification Plug can be left in the address socket or removed. If it is left in the address socket of the PROFIBUS Module, the address of the ECOFAST PROFIBUS module cannot be altered using P0918.

When the inverter first reads and stores the address from the Identification Plug a temporary warning condition is presented by the inverter, this is normal.

#### **CAUTION**

Do not insert or remove the identification plug while voltage is applied.

#### **Setting the Address using Parameter P0918**

Setting the PROFIBUS bus address using P0918 requires the fitting of a Basic Operator Panel (BOP) or an Advanced Operator Panel (AOP) to the inverter.

#### NOTE

The PROFIBUS address cannot be set via P0918, if the identification plug is fitted.

To set the PROFIBUS address using an operator panel, the following procedure should be performed (see also Changing parameters with the BOP on page 50):

- 1. Using the and keys, select P0918 on the Operator Panel display.
- 2. When P0918 is displayed, press (P) to access the parameter.
- 3. Using the and keys, select the required address (1 to 126 are valid addresses).
- 4. Press P to accept the address.
- 5. The new PROFIBUS Address is then stored in P0918.

## 3.6 Quick commissioning (P0010=1)

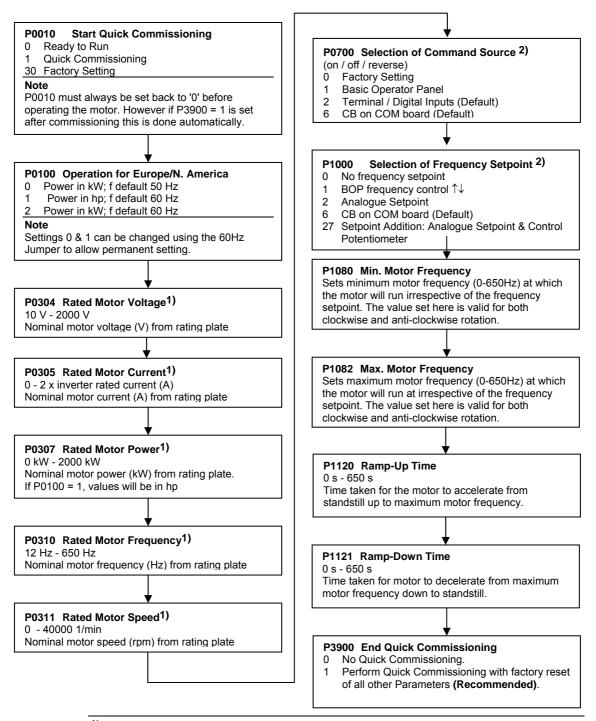
Mechanical and electrical installation of the inverter must be completed before running "Quick Commissioning".

It is **important** that the parameter P0010 is used for commissioning and P0003 for selecting the parameter level. Quick commissioning particularly uses parameters concerning the motor data and the acceleration and deceleration times. Quick commissioning is ended with P3900. If this parameter is set to 1, it makes the required motor calculations and sets all parameters which are not part of the quick commissioning to the default values.

#### **NOTE**

Parameter P0399 = 0 must be set before starting quick commissioning because it is not possible to change the motor data in the works default setting. Once quick commissioning has been completed, P0399 = 2 must be set.

#### Flow chart Quick Commissioning (Level 1 Only)



- 1) related parameters please refer to motor rating plate drawing.
- Denotes parameters that contain more detailed lists of possible settings for use in specific applications. Please refer to the Parameter List.

#### Motor data for parameterization

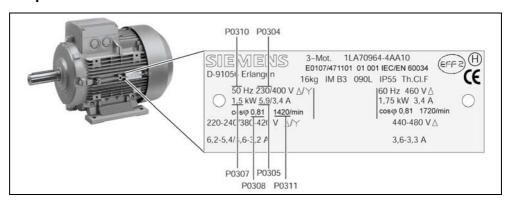


Figure 3-5 Typical Motor Rating Plate, Example

#### **NOTICE**

P0308 & P0309 are with BOP/AOP only visible if P0003  $\geq$  2. Only one of the parameters is shown depending on the settings of P0100.

Changing motor parameters is not possible unless P0010 = 1 (factory setting) and P004 = 0 or 3.

Ensure that the inverter is configured correctly to the motor.

## 3.6.1 Reset to Factory default

To reset all parameters to the factory default settings; the following parameters should be set as follows:

- 1. Set P0010 = 30
- 2. Set P0970 = 1



#### **WARNING**

A factory reset will set the command source to DIN 1 (On/(OFF1). Therefore make sure that after a factory reset, the motor cannot start unintentionally from an command via DIN1 (e.g. by a photocell or a BERO).

If a factory reset has been done (P0010 = 30 and P0970 = 1), the command source and the frequency setpoint source are set to "Terminals" and "Analog setpoint" respectively.

To re-establish the ECOFAST default settings, set the following:

- P0700 = 6 (Command source via communications network)
- P1000 = 6 (Frequency setpoint source via communications network)

#### **NOTICE**

- The reset process can take up to 3 minutes to complete.
- Refer to Parameter P3900 for description on saving motor data sets while performing a reset to the factory defaults.

## 3.7 General operation

For a full description of standard and extended parameters refer to the Parameter List.

#### **NOTICE**

- The inverter does not have a main power switch and is live when the power supply is connected. It waits, with the output disabled, for an ON signal via the selected command source.
- If a BOP or an AOP is fitted and the output frequency is selected to be displayed (P0005 = 21) the corresponding setpoint is displayed approximately every 1.0 seconds while the inverter is stopped.
- The inverter is programmed at the factory for standard applications on Siemens four-pole standard motors that have the same power rating as the inverters.
   When using other motors it is necessary to enter the specifications from the motor's rating plate. See Figure 3-5 for details on how to read motor data.
- Changing motor parameters is not possible unless P0010 = 1 and P004 = 0 or 3.
- You must set P0010 back to 0 in order to initiate a run.

## 3.7.1 Modes of Operation

#### **Operation via Communication options**

The most common mode of operation is via communications options (PROFIBUS or AS-Interface). All setpoints and commands are given via Communication options.

#### Operation via Keypad

It is also possible to operate the MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST via a Keypad (e.g., Basic Operator Panel or Advanced Operator Panel).

The Basic Operator Panel (BOP) – Part Number: 6SE6400-0BP00-0AA0 is housed in an Operator Panel Mounting Kit (6SE6401-1DF00-0AA0) and connected via the Interface Link Cable to the Inverter serial comms port. This arrangement is shown below.

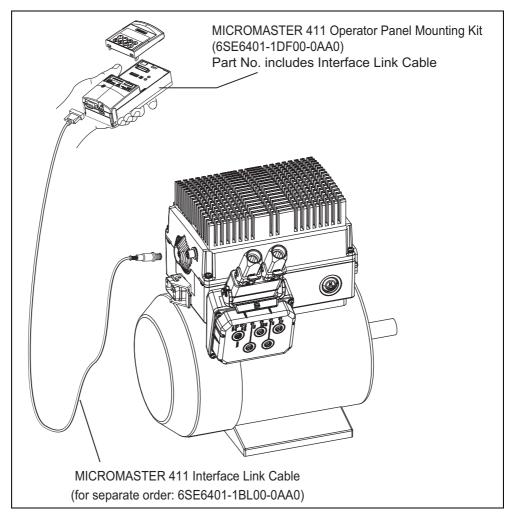


Figure 3-6 Connect BOP/AOP with the MICROMASTER 411

#### **Prerequisites**

- P0010 = 0 (in order to initiate the run command correctly).
- P0700 = 1 (enables the start/stop button on the BOP).
- P1000 = 1 (this enables the motor potentiometer setpoints).

Press the green Button to start the motor.

Press the Button while the motor is turning. Motor speed increases to 50 Hz.

When the inverter reaches 50 Hz, press the Button . Motor speed and display is decreased.

Change the direction of rotation with the Button .

ation with the Button

The red button stops the motor 0.

## 3.7.2 Stopping the Motor

If an OFF command is given via the selected command source, the OFF command will override the frequency setpoint setting and bring the motor to a controlled stop at the parameterized ramp down time.

## 3.7.3 If the Motor does not start up

Refer to Chapter 5.

### 3.7.4 If a fault occurs

- 1. Switch the Inverter off.
- 2. Disconnect and reconnect the power supply.
- 3. Switch on again.
- 4. Give a fault acknowledge command via the selected command source (DIN, BOP/AOP or Communications option.

Switch OFF if the fault condition persists.

## 4 System Parameters

## This Chapter contains:

- An introduction to the system parameters
- An overview about the parameter structure

4.1	Introduction to System Parameters	66
4.1.1	Access Levels	66
4.2	Parameter Structure	67

## 4.1 Introduction to System Parameters

Parameters can be changed either locally or remotly:

- Locally: by using a Basic Operator Panel (BOP) or an Advanced Operator Panel (AOP). Both are optional devices that must be ordered separately.
- Remotly: by using the communications network or a PC-based commissioning tool connected to the serial interface of the inverter.

#### **NOTE**

Full details of the COMBIMASTER 411 /MICROMASTER 411 Parameters can be found in the separate document "COMBIMASTER 411/MICROMASTER 411 – Parameter List".

It is included in the CD ROM delivered with the product.

Parameters may be changed and set (using the BOP) to adjust the desired properties of the inverter, such as ramp times, minimum and maximum frequencies etc. The parameter numbers selected and the setting of the parameter values are indicated on the optional five-digit LCD display.

- rxxxx indicates a display parameter, Pxxxx a setting parameter.
- P0010 initiates "Quick Commissioning". Set P0010 to 1.
- The inverter will not run unless P0010 is set to 0 after it has been accessed.
   This function is automatically performed if P3900 > 0.
- P0004 acts as a filter, allowing access to parameters according to their functionality group.
- **Busy Message**: In some cases when changing parameter values the display on the BOP shows 6059 for maximum of five seconds. This means the inverter is busy with tasks of higher priority.

#### 4.1.1 Access Levels

There are three access levels available to the user; Standard, Extended and Expert. The level of access is set by parameter P0003. For most applications, the Standard and Extended levels are sufficient.

The number of parameters that appear within each functional group depends on the access level set in parameter P0003. For further details regarding parameters, see the Parameter List on the Documentation CD-ROM.

#### 4.2 Parameter Structure

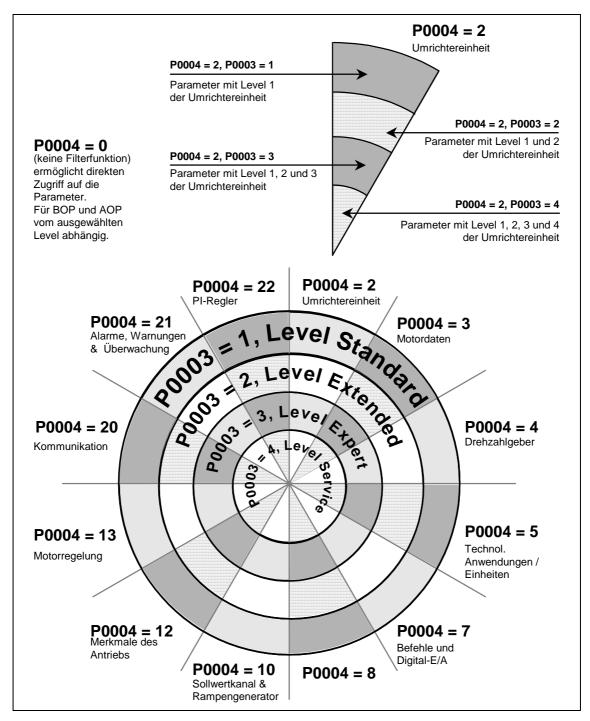


Figure 4-1 Parameter Structure with Filter (P0004)

## 5 Troubleshooting

## This Chapter contains:

- An overview of the operating statuses of the inverter with LED
- Notes on troubleshooting with the BOP
- A list of the alarms and fault messages

5.1	Troubleshooting with the Inverter LED	70
5.2	Troubleshooting with the PROFIBUS LED	71
5.3	Troubleshooting with the Basic Operator Panel	72
5.4	Faults and Alarms	73
5.4.1	Fault messages	73
5.4.2	Alarm messages	78

5 Troubleshooting Issue 06/04



#### **WARNINGS**

- Repairs on equipment may only be carried out by Service Center Drives
  authorized by Siemens or by authorized personnel who are thoroughly
  acquainted with all the warnings and operating procedures contained in this
  manual.
- Any defective parts or components must be replaced using parts contained in the relevant spare parts list.
- Disconnect the power supply before unplugging and opening the equipment for access. The user must wait for 5 minutes before accessing any terminals.

## 5.1 Troubleshooting with the Inverter LED

Check the status of the LED located within the control potentiometer. A list of the LED status indications are given in Table 5-1 below.

Table 5-1 Inverter LED Indication

Condition	Status
200 ms on/800 ms off	Power On/Ready
Continuous on	Running
800 ms on/200 ms off	Warning (general)
500 ms on/500 ms off	Trip (general)
Off	Off/Mains supply fault/No inverter power

## 5.2 Troubleshooting with the PROFIBUS LED

The three-colored LED display is on the front panel of the PROFIBUS-DP communication board. It provides instantaneous information about the status of the board.

Possible LED displays are explained in the Table 5-2 below.

Table 5-2 LED display on PROFIBUS communication Module

LED		Diagnostic information
off		No power supply
red	flashing fast	Invalid PROFIBUS address on DIL switch (126/127 is invalid) or hardware fault or software error
	on	Startup and no communication (yet) with the converter or new communication board configuration, after modification of a board parameter. If this status is steady, then the converter or PROFIBUS optional board is defective.
orange	flashing	Communication link to converter has been established. No connection to PROFIBUS, e.g. PROFIBUS connector is not inserted or PROFIBUS master disconnected.
	on	Communication link to converter and connection to PROFIBUS have been established, but no cyclical data exchange is taking place.
green	flashing	Cyclical process data exchange in progress, but setpoints invalid (control word = 0), e.g. because SIMATIC master is in "Stop" state
	on	Cyclical process data exchange in progress and o.k.

#### **NOTES**

- If a class 2 master with acyclical communication (PC or HMI) is installed, but no class 1 master with cyclical data exchange, then the LED displays "orange on".
- When the "DI/AI" input is used as an analog input, the LED will not illuminate
  when it receives an input signal. This is due to the 10 V threshold of the LED,
  since the analog voltage supply is only 0 to 10 V. When used as a digital input
  the LED will illuminate because it is supplied with a 24 V signal.

5 Troubleshooting Issue 06/04

## 5.3 Troubleshooting with the Basic Operator Panel

Warnings and faults are displayed on the BOP with Axxx and Fxxx respectively.

If the motor fails to start when the ON command has been given:

- Check that P0010 = 0.
- Check that a valid ON signal is present.

P0700 = 1 (BOP)

P0700 = 2 (Terminal/digital input)

P0700 = 6 (Communications network)

Check that a setpoint is present

P1000 = 1 (BOP)

P1000 = 2 (Analogue Setpoint)

P1000 = 6 (Communication)

P1000 = 27 (Setpoint-addition)

If the motor fails to run after changing the parameters, set P0010 = 30 then P0970 = 1 and press to reset the inverter to the factory default parameter values.

#### **NOTE**

For the MICROMASTER 411 ECOFAST the motor data must relate to the inverter data power range and voltage.

Issue 06/04 5 Troubleshooting

# 5.4 Faults and Alarms

# 5.4.1 Fault messages

In the event of a failure, the inverter switches off and a fault code appears on the display.

### NOTE

To reset the fault code, one of the methods listed below can be used:

Method 1: Cycle the power to the drive

Method 2: Give a fault acknowledge command via the selected command source

(DIN, BOP/AOP or Communications option).

### **OFF Commands**

OFF1 Causes the motor to come to a standstill at the selected ramp-down time

OFF2 Causes the motor to coast to a standstill (pulses disabled)

Fault messages are stored in parameter r0947 under their code number (e.g. F0003 = 3). The associated error value is found in parameter r0949. The value 0 is entered if a fault has no error value. It is furthermore possible to read out the point in time that a fault occurred (r0948) and the number of fault messages (P0952) stored in Parameter r0947.

F0001 OverCurrent OFF2

# Possible Causes

- Motor power (P0307) does not correspond to the inverter power (r0206)
- Motor leads are too long
- Motor lead short circuit
- > Earth faults

# Diagnose & Remedy

Check the following:

- 1. Motor power (P0307) must correspond to inverter power (r0206)
- 2. Cable length limits must not be exceeded
- 3. Motor cable and motor must have no short-circuits or earth faults
- 4. Motor parameters must match the motor in use
- 5. Value of stator resistance (P0350) must be correct
- 6. Motor must not be obstructed or overloaded
- > Increase the ramp time
- Reduce the boost level (V/f control: P1311 & P1312)

5 Troubleshooting Issue 06/04

# F0002 OverVoltage

OFF2

#### **Possible Causes**

- DC-link controller disabled (P1240 = 0)
- > DC-link voltage (r0026) exceeds trip level (P2172)
- Overvoltage can be caused either by too high main supply voltage or if motor is in regenerative mode. Regenerative mode can be caused by fast ramp downs or if the motor is driven from an active load.

## Diagnose & Remedy

Check the following:

- 1. Supply voltage (P0210) must lie within limits indicated on rating plate
- DC-link voltage controller must be enabled (P1240) and parameterized properly
- 3. Ramp-down time (P1121) must match inertia of load
- 4. Required braking power must lie within specified limits

# F0003 UnderVoltage

OFF2

#### **Possible Causes**

- Main supply failed
- > Shock load outside specified limits

### Diagnose & Remedy

Check the following:

- 1. Supply voltage (P0210) must lie within limits indicated on rating plate
- 2. Supply must not be susceptible to temporary failures or voltage reductions

# F0004 Inverter Over Temperature

OFF2

#### **Possible Causes**

- > Ventilation inadequate
- Ambient temperature is too high

### Diagnose & Remedy

Check the following:

- 1. Load conditions and duty cycle must be appropriate
- 2. Pulse frequency (P1800) must be set to default value
- 3. Ambient temperature could be higher than specified for the inverter

# F0005 Inverter I<sup>2</sup>t

OFF2

### **Possible Causes**

- > Inverter overloaded
- Duty cycle too demanding
- Motor power (P0307) exceeds inverter power capability (r0206)

## Diagnose & Remedy

Check the following:

- 1. Load duty cycle must lie within specified limits
- 2. Motor power (P0307) must match inverter power (r0206)

## **F0011** Motor Over Temperature

OFF1

### **Possible Causes**

Motor overloaded

# Diagnose & Remedy

Check the following:

- 1. Load duty cycle must be correct
- 2. Motor nominal overtemperatures (P0626-P0628) must be correct
- Motor temperature warning level (P0604) must match

Issue 06/04 5 Troubleshooting

# F0012 Inverter temp. signal lost OFF2

#### **Possible Causes**

Wire breakage of inverter temperature (heatsink) sensor

### F0035 Auto restart after n

OFF2

#### **Possible Causes**

Auto restart attempts exceed value of P1211

# F0041 Motor Data Identification Failure

OFF2

### **Possible Causes**

Motor data identification failed.

Fault value = 0: Load missing

- 1: Current limit level reached during identification.
- 2: Identified stator resistance less than 0.1 % or greater than 100 %.
- 3: Identified rotor resistance less than 0.1 % or greater than 100 %.
- 4: Identified stator reactance less than 50 % and greater than 500 %
- 5: Identified main reactance less than 50 % and greater than 500 %
- 6: Identified rotor time constant less than 10 ms or greater than 5 s
- 7: Identified total leakage reactance less than 5 % and greater than 50 %
- 8: Identified stator leakage reactance less than 25 % and greater than 250 %
- 9: Identified rotor leakage inductance less than 25 % and greater than 250 %
- 20: Identified IGBT on-voltage less than 0.5 V or greater than 10 V
- 30: Current controller at voltage limit
- 40: Inconsistency of identified data set, at least one identification failed

Percentage values based on the impedance Zb = Vmot,nom / sqrt(3) / Imot,nom

#### Diagnose & Remedy

- Fault value = 0: Check that the motor is connected to the inverter
- Fault value = 1-40: Check if motor data in P0304 to P0311 are correct

Check what type of motor wiring is required (star, delta).

### F0051 Parameter EEPROM Fault

OFF2

### **Possible Causes**

Read or write failure while saving non-volatile parameter

### Diagnose & Remedy

- Factory Reset and new parameterization
- 2. Contact Customer Support / Service Department

### F0052 Power stack Fault

OFF2

### **Possible Causes**

Read failure for power stack information or invalid data

### Diagnose & Remedy

Hardware defect, contact Customer Support / Service Department

# F0060 Asic Timeout

OFF2

## **Possible Causes**

Internal communications failure

### Diagnose & Remedy

- If fault persists, change inverter
- Contact Service Department

5 Troubleshooting Issue 06/04

F0070	CB setpoint fault	OFF2
	Possible Causes No setpoint values from CB (communication board) during telegram off time	
	Diagnose & Remedy Check CB and communication partner	
F0071	USS (BOP-link) setpoint fault	OFF2
	Possible Causes  No setpoint values from USS during telegram off time	
	Diagnose & Remedy Check USS master	
F0072	USS (COMM link) setpoint fault	OFF2
	Possible Causes  No setpoint values from USS during telegram off time	
	Diagnose & Remedy Check USS master	
F0085	External Fault	OFF2
	Possible Causes External fault triggered via for example terminal inputs	
	Diagnose & Remedy Disable for example terminal input for fault trigger	
F0101	Stack Overflow	OFF2
	Possible Causes Software error or processor failure	
	Diagnose & Remedy Run self test routines	
F0221	PID Feedback below min. value	OFF2
	Possible Causes PID Feedback below min. value P2268	
	Diagnose & Remedy  ➤ Change value of P2268  ➤ Adjust feedback gain	
F0222	PID Feedback above max. value	OFF2
	Possible Causes PID feedback above max. value P2267	
	Diagnose & Remedy  ➤ Change value of P2267  ➤ Adjust feedback gain	

Issue 06/04 5 Troubleshooting

## F0450 BIST Tests Failure

OFF2

### **Possible Causes**

Fault value Some power section tests have failed = 1:

2: Some control board tests have failed

4: Some functional tests have failed

16: Internal RAM failed on power-up check

#### Diagnose & Remedy

Hardware defect, contact Customer Support / Service Department

## F0452 Belt Failure Detected

OFF2

### **Possible Causes**

Load conditions on motor indicate belt failure or mechanical fault.

### Diagnose & Remedy

Check the following:

- 1. No breakage, seizure or obstruction of drive train.
- 2. If using an external speed sensor, check for correct function. Check parameters:
  - P2192 (delay time for permitted deviation)
- 3. If using the torque envelope, check parameters:
  - P2182 (threshold frequency f1)
  - > P2183 (threshold frequency f2)
  - > P2184 (threshold frequency f3)
  - P2185 (upper torque threshold 1)
     P2186 (lower torque threshold 1)

  - P2187 (upper torque threshold 2)
  - > P2188 (lower torque threshold 2)
  - > P2189 (upper torque threshold 3
  - > P2190 (lower torque threshold 3)
  - > P2192 (delay time for permitted deviation)

5 Troubleshooting Issue 06/04

# 5.4.2 Alarm messages

### A0501 Current Limit

### **Possible Causes**

- Motor power (P0307) does not correspond to the inverter power (P0206)
- Motor leads are too long
- Earth faults

### Diagnose & Remedy

Check the following:

- Motor power (P0307) must correspond to inverter power (r0206)
- > Cable length limits must not be exceeded
- Motor cable and motor must have no short-circuits or earth faults
- Motor parameters must match the motor in use
- > Value of stator resistance (P0350) must be correct
- Motor must not be obstructed or overloaded
- Increase the ramp-up-time.
- > Reduce the boost level (V/f control: P1311 & P1312, Vector control: P1610 & P1611)

# A0502 Overvoltage limit

### **Possible Causes**

- Overvoltage limit is reached
- This warning can occur during ramp down, if the dc-link controller is disabled (P1240 = 0)

### Diagnose & Remedy

Check the following:

- > Supply voltage (P0210) must lie within limits indicated on rating plate
- > DC-link voltage controller must be enabled (P1240) and parameterized properly
- > Ramp-down time (P1121) must match inertia of load
- Required braking power must lie within specified limits

# A0503 UnderVoltage Limit

### **Possible Causes**

- Main supply failed
- Main supply (P0210) and consequently DC-link voltage (r0026) below specified limit (P2172)

### Diagnose & Remedy

- Supply voltage (P0210) must lie within limits indicated on rating plate
- Supply must not be susceptible to temporary failures or voltage reductions
- ➤ Enable kinetic buffering (P1240 = 2)

# A0504 Inverter OverTemperature

### Possible Causes

Warning level of inverter heat-sink temperature (P0614) is exceeded, resulting in pulse frequency reduction and/or output frequency reduction (depending on parameterization in P0610)

## Diagnose & Remedy

Check the following:

- Load conditions and duty cycle must be appropriate
- Fan must turn when inverter is running
- Pulse frequency (P1800) must be set to default value
- Ambient temperature could be higher than specified for the inverter

# A0505 Inverter I<sup>2</sup>t

#### **Possible Causes**

Warning level (P0294) exceeded, output frequency and/or pulse frequency will be reduced if parameterized (P0290)

## Diagnose & Remedy

Check the following:

- Load duty cycle must lie within specified limits
- Motor power (P0307) must match inverter power (r0206)

# A0511 Motor OverTemperature

### **Possible Causes**

- Motor overloaded
- Load duty cycle too high

### Diagnose & Remedy

Independently of the kind of temperature determination check the following:

- Load duty cycle must be correct
- Motor nominal overtemperatures (P0626-P0628) must be correct
- Motor temperature warning level (P0604) must match

# A0535 Braking Resistor Hot

### Diagnose & Remedy

- Increase duty cycle P1237
- Increase ramp down time P1121

## A0541 Motor Data Identification Active

### **Possible Causes**

Motor data identification (P1910) selected or running

# A0600 RTOS Overrun Warning

# A0700 CB warning 1

# Possible Causes

CB (communication board) specific

## Diagnose & Remedy

See CB user manual

# A0701 CB warning 2

### **Possible Causes**

CB (communication board) specific

## Diagnose & Remedy

See CB user manual

5 Troubleshooting Issue 06/04

# A0702 CB warning 3

**Possible Causes** 

CB (communication board) specific

Diagnose & Remedy

See CB user manual

# A0703 CB warning 4

**Possible Causes** 

CB (communication board) specific

Diagnose & Remedy

See CB user manual

# A0704 CB warning 5

**Possible Causes** 

CB (communication board) specific

Diagnose & Remedy

See CB user manual

# A0705 CB warning 6

**Possible Causes** 

CB (communication board) specific

Diagnose & Remedy

See CB user manual

# A0706 CB warning 7

**Possible Causes** 

CB (communication board) specific

Diagnose & Remedy

See CB user manual

# A0707 CB warning 8

Possible Causes

CB (communication board) specific

Diagnose & Remedy

See CB user manual

# A0708 CB warning 9

**Possible Causes** 

CB (communication board) specific

Diagnose & Remedy

See CB user manual

# A0709 CB warning 10

#### **Possible Causes**

CB (communication board) specific

### Diagnose & Remedy

See CB user manual

## A0710 CB communication error

#### **Possible Causes**

Communication with CB (communication board) is lost

#### Diagnose & Remedy

Check CB hardware

# A0711 CB configuration error

#### **Possible Causes**

CB (communication board) reports a configuration error.

### Diagnose & Remedy

Check CB parameters

### A0910 Vdc-max controller de-activated

# **Possible Causes**

Vdc max controller has been de-activated, since controller is not capable of keeping DC-link voltage (r0026) within limits (P2172).

- > Occurs if main supply voltage (P0210) is permanently too high
- Occurs if motor is driven by an active load, causing motor to go into regenerative mode
- Occurs at very high load inertias, when ramping down

## Diagnose & Remedy

Check the following:

- > Input voltage (P0210) must lie within range
- Load must be match

## A0911 Vdc-max controller active

### **Possible Causes**

Vdc max controller is active; so ramp-down times will be increased automatically to keep DC-link voltage (r0026) within limits (P2172).

## A0912 Vdc-min controller active

### **Possible Causes**

Vdc min controller will be activated if DC-link voltage (r0026) falls below minimum level (P2172). The kinetic energy of the motor is used to buffer the DC-link voltage, thus causing deceleration of the drive!

So short mains failures do not necessarily lead to an undervoltage trip.

5 Troubleshooting Issue 06/04

# A0920 ADC parameters not set properly

#### **Possible Causes**

ADC parameters should not be set to identical values, since this would produce illogical results.

Fault value = 0: Parameter settings for output identical

- 1: Parameter settings for input identical
- 2: Parameter settings for input do not correspond to ADC type

# A0921 DAC parameters not set properly

### **Possible Causes**

DAC parameters should not be set to identical values, since this would produce illogical results.

Fault value = 0: Parameter settings for output identical

- 1: Parameter settings for input identical
- 2: Parameter settings for output do not correspond to DAC type

# A0922 No load applied to inverter

#### **Possible Causes**

No Load is applied to the inverter.

As a result, some functions may not work as under normal load conditions.

# A0923 Both JOG Left and JOG Right are requested

### **Possible Causes**

Both JOG right and JOG left (P1055/P1056) have been requested. This freezes the RFG output frequency at its current value.

# A0936 PID Autotuning Active

### **Possible Causes**

PID Autotuning (P2350) selected or running

# A0952 Belt Failure Warning

### **Possible Causes**

Load conditions on motor indicate belt failure or mechanical fault.

# Diagnose & Remedy

Check the following:

- 1. No breakage, seizure or obstruction of drive train.
- 2. If using an external speed sensor, check for correct function. Check parameters:
  - P2192 (delay time for permitted deviation)
- 3. If using the torque envelope, check parameters:
  - > P2182 (threshold frequency f1)
  - P2183 (threshold frequency f2)
  - > P2184 (threshold frequency f3)
  - > P2185 (upper torque threshold 1)
  - P2186 (lower torque threshold 1)
  - P2187 (upper torque threshold 2)P2188 (lower torque threshold 2)
  - P2189 (upper torque threshold 3)
  - > P2190 (lower torque threshold 3)
  - > P2192 (delay time for permitted deviation)

Issue 06/04 6 Specifications

# 6 Specifications

# This Chapter contains:

- The common technical data to the MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST Inverters
- The wire sizes and terminal torques
- Divided into several tables an overview of the specific technical data of every MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST Inverter

6.1	Technical Data	84
6.2	Case Size Rating Information	85
6.3	External Fuene and Circuit Broakers	Ω7

# 6.1 Technical Data

Table 6-1 COMBIMASTER 411 ECOFAST / MICROMASTER 411 ECOFAST Performance Ratings

Feature	Specification			
Power supply Operating Voltage & Power Ranges	380 to 480 V $\pm$ 10% 3AC 0.37 kW $-$ 3.0 KW (MICROMASTER 411 ECOFAST) 380 to 480 V $\pm$ 10% 3AC 0.37 kW $-$ 2.2 kW (COMBIMASTER 411 ECOFAST)			
Protection Level	IP65 for MICROMASTER 411 ECOFAST IP55 for COMBIMASTER 411 ECOFAST			
Operating Temperature	-10°C to +40°C (50°C with derating)			
Storage Temperature	-40 °C to +70 °C			
Relative humidity	99% RH – (non-condensing)			
Installation Altitudes	Up to 1000m above sea level without derating			
Control Method	Linear V/f; Flux Current Control (FCC); Quadratic V/f; Multi-point V/f (parameterizable).			
Overload Capability	1.5 * nominal output current for 60 seconds (every 300 seconds)			
Electromagnetic Compatibility	EMC filters to EN55011 Class A			
Protection Features	<ul> <li>Undervoltage,</li> <li>Overload,</li> <li>Short circuit,</li> <li>Stall Prevention,</li> <li>Motor Overtemperature ft, (Option for PTC),</li> <li>Inverter Overtemperature,</li> <li>Parameter interlock</li> </ul>			
Input Frequency	47 to 63 Hz			
Setpoint Resolution	0.01Hz Digital, 0.01 Hz Serial, 10 bit Analog			
Output Frequency Resolution	0.01Hz Digital, 0.01 Hz Serial, 10 bit Analog			
Pulse Frequency	2kHz to 16kHz (2kHz steps) 4kHz default			
Digital Inputs (Requires ECOFAST PROFIBUS module)	3 programmable inputs. 2 Digital Inputs & 1 Analog input which can be configured as a third digital input.			
Fixed Frequencies	7 programmable			
Skip Frequencies	4 programmable			
Relay Outputs (Requires ECOFAST PROFIBUS module)	1 programmable 24 V DC / 0.5 A (resistive)			
Analogue Input (Requires ECOFAST PROFIBUS module)	1 for setpoint or PI 0 to +10 V Input (Also used for DIN4)			
Serial Interface	RS-232.			
Design / Manufacture	In accordance with ISO 14001			
Conformance with Standards	CE			
CE labelled	Conformity with EC Low Voltage Directive 73/23/EEC and Electromagnetic Compatibility Directive 89/336/EEC			

Issue 06/04 6 Specifications

Cos Ø	≥ 0.95	
Inverter Efficiency	94 % to 97 % at maximum power	
Inrush Current	Less than 4 A for case size B and less than 7.7 A for case size C.	
Braking	DC braking, COMPOUND braking: EM module (electromechanical brake control module) and REM module (resistor and electromechanical brake control module) available as options.	

# 6.2 Case Size Rating Information

Table 6-2 Case Size B

2 pole: Fra	ame size			71M	71M	80M	80M		90S	
4 pole: Frame size			71M	80M	80M	90S		90L		
I Motor Output Rating:			kW hp	0.37 0.5	0.55 0.75	0.75 1.0	1.1 1.5		1.5 2.0	
Input Volta	age range:		V	3 AC 380 - 480 ± 10 %						
Input Freq	uency:		Hz			47 – 6	3			
Output Fre	equency:									
MICROMA	ASTER 41	1	Hz			0 - 65	50			
COMBIMA	ASTER 41	1 [2 pole]	112			0 – 10	00			
COMBIMA	ASTER 41	1 [4 pole]				0 – 14	10			
Inrush Cui	rrent:		Α			< 4				
Input Curr	ent:		Α	1.6	2.1	2.8	4.2	.2 5.8		
Output Cu	rrent (max	():	Α	1.2	1.6	2.1	3.0	3.0 4.0		
Internal fu	se (non-re	placeable):	Α	10						
Power Sup (max)	pply Lead	cross-section	mm <sup>2</sup>	4						
		without filter	1UA1	4.75 / 9.6	4.75 / 11.	2 4.75 / 1	2.8 4.75 /	14.5	4.75 / 17.5	
	2 pole	without filter	1UA2				_	-		
	2 poic	filtered	1UA1	4.75 / 9.6	4.75 / 11.	2 4.75 / 1	2.8 4.75	14.5	4.75 / 17.5	
Weight		intered	1UA2	5.0 / 9.8	5.0 / 11.4	5.0 / 1	3 5.0 /	14.7	5.0 / 17.7	
vveigni		without filter	1UA1	4.75 / 10.6	4.75 / 12.	6 4.75 /	14 4.75 /	16.9	4.75 / 20.2	
	4 pole	without filter	1UA2				-	-		
	7 Pole	4 pole filtered	1UA1	4.75 / 10.6	4.75 / 12.	6 4.75 /	14 4.75	16.9	4.75 / 20.2	
		intered	1UA2	5.0 / 10.8	5.0 / 12.8	5.0 / 14	4.2 5.0 /	17.1	5.0 / 20.4	

Table 6-3 Case Size C

2 pole: Fr	ame size			90L	MICROMASTER 411 ECOFAST	
4 pole: Frame size				100L	(wall mounted variants) only	
Motor Output Rating:			KW	2.2	3.0	
Motor Ou	tput Kating	<b>J</b> :	hp	3.0	4.0	
Input Volt	age range	•	V	3 AC 380 –	480 ± 10 %	
Input Fred	quency:		Hz	47	- 63	
Output Fr	equency:					
MICROM	ASTER 41	1	Hz	0 -	650	
COMBIMA	ASTER 41	1 [2 pole]	112	0 –	100	
COMBIMA	ASTER 41	1 [4 pole]		0 –	140	
Inrush Cu	rrent:		Α	<	7.7	
Input Cur	rent:		Α	7.8	10	
Output Cu	urrent (max	x):	Α	5.9	7.7	
Internal fu	ıse (non-re	eplaceable):	Α	20 30		
Power Su (max)	pply Lead	cross-section	mm <sup>2</sup>	4		
		without filter	1UA1	7.2 / 22.5	7.2 / 28.8	
	0 1-	without filter	1UA2			
	ıt	filtered	1UA1	7.2 / 22.5	7.2 / 28.8	
Weight		ilitered	1UA2	7.7 / 23		
		without filter	1UA1	7.2 / 28.8	7.2 / 31.8	
		without filter	1UA2			
	т роіс	filtered	1UA1	7.2 / 22.5	7.2 / 28.8	
	line		1UA2	7.7 / 29.3		

Issue 06/04 6 Specifications

# 6.3 External Fuses and Circuit Breakers

The ECOFAST system is designed to incorporate a system fuse rated at 40 A. In standalone applications, the user may choose to use external fuses/circuit breakers in accordance with the list in Table 6 4 below.

Table 6-4 External Fuses and Circuit Breakers

Inverter	Pov	Power Case		Fuses	Circuit	
iliverter	kW	Нр	Size	ruses	Breakers	
	0.37	0.5	В	3NA3803	3RV1021-1CA10	
COMBIMASTER 411 ECOFAST/	0.55	0.75	В	3NA3803	3RV1021-1DA10	
MICROMASTER 411 ECOFAST	0.75	1.0	В	3NA3803	3RV1021-1EA10	
380 V to 480 V 3 AC	1.1	1.5	В	3NA3803	3RV1021-1GA10	
(without filter)	1.5	2.0	В	3NA3803	3RV1021-1HA10	
	2.2	3.0	С	3NA3805	3RV1021-1JA10	
	3.0	4.0	С	3NA3805	3RV1021-4KA10	
	0.37	0.5	В	3NA3803	3RV1021-1CA10	
COMBIMASTER 411 ECOFAST/	0.55	0.75	В	3NA3803	3RV1021-1DA10	
MICROMASTER 411 ECOFAST	0.75	1.0	В	3NA3803	3RV1021-1EA10	
380 V to 480 V 3 AC	1.1	1.5	В	3NA3803	3RV1021-1GA10	
(with Class B filter)	1.5	2.0	В	3NA3803	3RV1021-1HA10	
	2.2	3.0	С	3NA3805	3RV1021-1JA10	
	3.0	4.0	С	3NA3805	3RV1021-1KA10	

6 Specifications Issue 06/04

# 7 ECOFAST Options

# This Chapter contains:

A listing of the available options of the MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST Inverter

7.1	Options – Non-inverter Mounted	90
7.2	Options – Inverter Mounted	90
7.2.1	ECOFAST PROFIBUS Module	91
7.2.2	Description	91
7.2.3	Functionality	91

# 7.1 Options – Non-inverter Mounted

Table 7-1 Options – Non-inverter Mounted

Description	Order No
Basic Operator Panel (BOP)	6SE6400-0BP00-0AA0
Advanced Operator Panel (AOP)	6SE6400-0AC00-0AA0
Operator Panel Mounting Kit	6SE6401-1DF00-0AA0
Interface Link Cable, serial	6SE6401-1BL00-0AA0
Connection Set for PC to Inverter	6SE6400-1PC00-0AA0
Connection Set for PC to AOP	6SE6400-0PA00-0AA0
BOP/AOP Door Mounting Kit for Single Inverter	6SE6400-0PM00-0AA0
5 m Cable Assembly for Door Mounting Kit	6SE6401-1CA00-0AA0
PROFIBUS Addressing Connector	6ES7194-1KB00-0XA0

# 7.2 Options – Inverter Mounted

The following ECOFAST options are ordered and pre-assembled with the delivered inverter:

- · Communication modules:
  - AS-Interface module or
  - ECOFAST PROFIBUS module
- Brake function modules:
  - EM module (Electromechanical brake control module) or
  - REM module (Resistor and electromechanical brake control module)

These options are ordered using "Option Codes" attached to the main order code for the inverter.

Option Order Codes can be obtained from the ECOFAST Product Catalogue.

## 7.2.1 ECOFAST PROFIBUS Module

The function of the ECOFAST PROFIBUS module is to provide a communications link between inverters of the MICROMASTER 4 product range and a higher-level automated system. This ECOFAST PROFIBUS module is specific to the MICROMASTER 411 ECOFAST and COMBIMASTER 411 ECOFAST Inverters.



# 7.2.2 Description

The ECOFAST PROFIBUS module is contained within the housing of the

Figure 7-1 ECOFAST PROFIBUS module

Options module attached to the side of the inverter.

Communication and external 24 V power supply is normally provided by the Hybrid Fieldbus cable.

Although the PROFIBUS module is powered directly from the inverter and bus communication is fully functional without an external power supply, we recommend the use of an external 24 V supply which is supplied through the Hybrid Fieldbus cable, otherwise the PROFIBUS I/Os cannot be used.

The ECOFAST system supports PROFIBUS networks utilizing either copper (Cu) or Fiber Optic (Fo) cables.

# 7.2.3 Functionality

- Cyclical process data exchange (PZD) in accordance with PROFIDrive Profile, version 2.0 or version 3.0
- · Parameter accessing:
- Cyclical accessing of parameters (PKW) in accordance with PROFIDrive Profile version 2.0
- OI
- Acyclical accessing of parameters (data block 47) in accordance with PROFIDrive Profile version 3.0
- Acyclical accessing of parameters (data block 100/data block 47) for the purpose of exchanging parameter values with a SIMATIC S7 CPU (Drive ES SIMATIC function block package)

- Acyclical accessing of parameters for SIMATIC HMI or Siemens Drive STARTER tool.
- Support of PROFIBUS control commands SYNC and FREEZE for synchronized data transfer between the master and several slaves
- Internode communication for direct exchange of process data between PROFIBUS slaves (only in conjunction with SIMATIC S7 at the present time).
- 3 External Inputs (2 Digital and 1 Analog).
- Digital Outputs (0.5 A, 24 V) overload protected.
- External Address Identification Plug connector.

For more details of the functionality and operation of the ECOFAST PROFIBUS Module, please refer to the COMBIMASTER 411 & MICROMASTER 411 PROFIBUS Module Operating Instructions in the Internet.

# 8 Electro-Magnetic Compatibility (EMC)

# This Chapter contains:

Information about the Electro-Magnetic Compatibility and its Certification.

8.1	Electro-Magnetic Compatibility (EMC)	94
8.1.1	Self-Certification	94
8.1.2	Technical Construction File	94
8.1.3	EC Type Examination Certificate	94
8.1.4	EMC Directive Compliance with Harmonics Regulations	94
8.1.5	Environment Classes of EMC performance	95
8.1.6	Environment: Filtered - for residential, commercial and light industry	96
8.1.7	EMC Compliance Tests	97
8.1.8	EMC Compliance	97

# 8.1 Electro-Magnetic Compatibility (EMC)

All manufacturers / assemblers of electrical apparatus which "performs a complete intrinsic function and is placed on the market as a single unit intended for the end user" must comply with the EMC directive EEC/89/336.

There are three routes for the manufacturer/assembler to demonstrate compliance:

# 8.1.1 Self-Certification

This is a manufacturer's declaration that the European standards applicable to the electrical environment for which the apparatus is intended have been met. Only standards that have been officially published in the Official Journal of the European Community can be cited in the manufacturer's declaration.

### 8.1.2 Technical Construction File

A technical construction file can be prepared for the apparatus describing its EMC characteristics. This file must be approved by a 'Competent Body' appointed by the appropriate European government organization. This approach allows the use of standards that are still in preparation.

# 8.1.3 EC Type Examination Certificate

This approach is only applicable to radio communication transmitting apparatus. All MICROMASTER units are certified for compliance with the EMC directive, when installed in accordance with the recommendations in Section 2 of this document.

# 8.1.4 EMC Directive Compliance with Harmonics Regulations

EN 61000-3-2 "Limits for harmonic current emissions (equipment input <= 16A per phase)".

All Siemens variable speed drives of the MICROMASTER, MIDIMASTER, MICROMASTER Eco and COMBIMASTER ranges, which are classified as "Professional Equipment" within the terms of the standard, fulfill the requirements of the standard.

# 8.1.5 Environment Classes of EMC performance

## **Environment: General Industrial**

Compliance with the EMC Product Standard for Power Drive Systems EN 61800-3 for use in **Second Environment (Industrial)** and **Restricted Distribution**.

Table 8-1 Environment - General Industrial

EMC Phenomenon		Standard	Level
Emissions: Radiated Emissions		EN 55011	Level A1
	Conducted Emissions	EN 61800-3	European Amendment EN61800-3-A13
Immunity:	Electrostatic Discharge	EN 61000-4-2	8 kV air discharge
	Burst Interference	EN 61000-4-4	2 kV power cables, 1 kV control
	Radio Frequency Electromagnetic Field	IEC 1000-4-3	26-1000 MHz, 10 V/m

## **Environment: Filtered Industrial**

This level of performance will allow the manufacturer/assembler to self-certify their apparatus for compliance with the EMC directive for the industrial environment as regards the EMC performance characteristics of the power drive system. Performance limits are as specified in the Generic Industrial Emissions and Immunity standards EN 50081-2 and EN 50082-2.

Table 8-2 Environment - Filtered Industrial

EMC Phenomenon		Standard	Level
Emissions:	Radiated Emissions	EN 55011	Level A1
	Conducted Emissions	EN 55011	Level A1
Immunity:	Supply Voltage Distortion	IEC 1000-2-4 (1993)	
	Voltage Fluctuations, Dips, Unbalance, Frequency Variations	IEC 1000-2-1	
	Magnetic Fields	EN 61000-4-8	50 Hz, 30 A/m
	Electrostatic Discharge	EN 61000-4-2	8 kV air discharge
	Burst Interference	EN 61000-4-4	2 kV power cables, 2 kV control
	Radio-frequency electromagnetic field, amplitude modulated	ENV 50 140	80-1000 MHz, 10 V/m, 80% AM, power and signal lines
	Radio-frequency electromagnetic field, pulse modulated	ENV 50 204	900 MHz, 10 V/m 50% duty cycle, 200 Hz repetition rate

# 8.1.6 Environment: Filtered - for residential, commercial and light industry

This level of performance will allow the manufacturer / assembler to self-certify compliance of their apparatus with the EMC directive for the residential, commercial and light industrial environment as regards the EMC performance characteristics of the power drive system. Performance limits are as specified in the generic emission and immunity standards EN 50081-1 and EN 50082-1.

Table 8-3 Environment - Filtered for Residential, Commercial and Light Industry

EMC Pheno	menon	Standard	Level
Emissions:	Radiated Emissions	EN 55011	Level A (Restricted Distribution)
	Conducted Emissions	EN 55011	Level B
Immunity:	Supply Voltage Distortion	IEC 1000-2-4 (1993)	
	Voltage Fluctuations, Dips, Unbalance, Frequency Variations	IEC 1000-2-1	
	Magnetic Fields	EN 61000-4-8	50 Hz, 30 A/m
	Electrostatic Discharge	EN 61000-4-2	8 kV air discharge
	Burst Interference	EN 61000-4-4	2 kV power cables, 2 kV control
	Radio-frequency electromagnetic field, amplitude modulated	ENV 50 140	80-1000 MHz, 10 V/m, 80% AM, power and signal lines
	Radio-frequency electromagnetic field, pulse modulated	ENV 50 204	900 MHz, 10 V/m 50% duty cycle, 200 Hz repetition rate

### **NOTES**

- COMBIMASTER 411 ECOFAST / MICROMASTER 411 ECOFAST inverters are intended exclusively for professional applications. Therefore, they do not fall within the scope of the harmonics emissions specification EN 61000-3-2.
- Class A filtered inverters can be used in this environment under "Restricted Distribution" (Professional Applications) in accordance with EN61800 Part 3.
- Dedicated EMC Product Standards can exist for this equipment/units/machine/plant, which the manufacturer must then observe.

# 8.1.7 EMC Compliance Tests

Table 8-4 EMC Compliance Table

Model	Remarks
Environment – General II	ndustrial
6SE6411-6U***-**A1	Unfiltered units, all voltages and powers
1UA1**-**U**	
1UA2**-**U**.	
Environment – Filtered Ir	ndustrial (All EU countries for year 2002)
6SE6411-6B***-**A1	Filtered units all voltages and powers
1UA1**-**B**	
1UA2**-**B**.	
* Denotes any value is allo	wed.

# 8.1.8 EMC Compliance

The MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST inverters will, when correctly installed and put to their intended use, satisfy the requirements of the EEC Directive 89/336/EEC concerning electromagnetic compatibility.

If the guidelines on installation to reduce the effects of electromagnetic interference are followed, the devices are suitable for installation in machines. According to the machinery directive, these machines must be separately certified.

Table 8-5 below lists the measured results for emissions of an immunity to interference for the MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST inverters.

Table 8-5 MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST Measured Results

Test Standard	Measurement	Test Value	Limit Value
RFI Emissions	Conducted via Mains Cable	150 kHz to 30 MHz	All devices – Class A
	Emitted by the inverter	30 MHz to 1 GHz	All devices – Class A

Issue 06/04 Appendices

# **Appendices**

# A Applicable Standards



# **European Low Voltage Directive**

The MICROMASTER product range complies with the requirements of the Low Voltage Directive 73/23/EEC as amended by Directive 98/68/EEC. The units are certified for compliance with the following standards:

EN 60146-1-1 Semiconductor inverters – General requirements and line commutated inverters

EN 60204-1 Safety of machinery – Electrical equipment of machines

# **European Machinery Directive**

The MICROMASTER product range does not fall under the scope of the Machinery Directive. However, the products have been fully evaluated for compliance with the essential Health & Safety requirements of the directive when used in a typical machine application. A Declaration of Incorporation is available on request.

## **European EMC Directive**

When installed according to the recommendations described in this manual, the MICROMASTER product range fulfils all requirements of the EMC Directive as defined by the EMC Product Standard for Power Drive Systems EN61800-3.

## ISO 14001

Siemens plc operates a quality and environmental management system, which complies with the requirements of ISO 14001.

## **ISO 9001**

Siemens plc operates a quality management system, which complies with the requirements of ISO 9001.

Appendices Issue 06/04

# **B** List of Abbreviations

AC AD	Alternating current Analog digital converter	DS EEC	Drive state European Economic
ADC	Analog digital converter		Community
ADR	Address	EEPR	Electrical erasable
AFM	Additional frequency	OM	programmable read-only
	modification	ELCB	3
AIN	Analog input	EM	Electromechanical Brake
AOP	Advanced operator panel	Brake	
	Analog output	EMC	Electro-magnetic compatibility
ASP	Analog setpoint	EMF	Electromotive force
ASVM	Asymmetric space vector	EMI	Electro-magnetic interference
500	modulation	FAQ	Frequently asked questions
BCC	Block check character	FCC	Flux current control
BCD	Binary-coded decimal code	FCL	Fast current limit
BI	Binector input	FF	Fixed frequency
BICO	Binector / connector	FFB FOC	Free function block
BO BOP	Binector output	FSA	Field orientated control Frame size A
С	Basic operator panel Commissioning	GSG	
СВ	Communication board		Global unique identifier
CCW	Counter-clockwise	HIW	Main actual value
CDS	Command data set	HSW	Main setpoint
CI	Connector input	HTL	High-threshold logic
CM	Configuration management	I/O	Input and output
CMD	Commando	IBN	Commissioning
CMM	COMBIMASTER	IGBT	Insulated gate bipolar
CO	Connector output		transistor
CO/BC	Connector output / Binector	IND	Sub-index
	output	JOG	Jog
COM	Common (terminal that is	KIB	Kinetic buffering
	connected to NO or NC)	KTY	
COM-	Communication link	LCD	Liguid crystal display
Link		LED	Light emitting diode
CT	Commissioning, read to run	LGE	Length
CT	Constant torque	MHB	Motor holding brake
CUT	Commissioning, run, read to	MM4	MICROMASTER 4th.
0144	run		Generation
CW	Clockwise	MOP	Motor potentiometer
DA	Digital analog converter	NC	Normally closed
DAC	Digital analog converter	NO	Normally open
DC	Direct current	NPN	Operating instructions
DDS	Drive data set	OPI PDS	Operating instructions
DIN DIP	Digital input DIP switch	PID	Power drive system PID controller (proportional,
	Digital output	רוח	integral, derivative)
וטטטו	Digital output		integral, derivative)

Issue 06/04 Appendices

PKE PKW	Parameter ID Parameter ID value	REM Brake	REM Module
PLC	Programmable logic controller	RFG	Ramp function generator
PLI	Parameter list	RFI	Radio-frequency interference
PPO	Parameter process data object	RPM	Revolutions per minute
PTC	Positive temperature	SCL	Scaling
	coefficient	SDP	Status display panel
PWE	Parameter value	SLVC	Sensorless vector control
PWM	Pulse-width modulation	STW	Control word
PX	Power extension	STX	Start of text
PZD	Process data	SVM	Space vector modulation
QC	Quick commissioning	TTL	Transistor-transistor logic
RAM	Random-access memory	USS	Universal serial interface
RCCB	Residual current circuit	VC	Vector control
	breaker	VT	Variable torque
RCD	Residual current device	ZSW	Status word

Appendices Issue 06/04

# **Suggestions and/or Corrections**

То:	Suggestions
Siemens AG	Corrections
Automation & Drives Group	For Publication/Manual:
SD VM 4 P.O. Box 3269	MICROMASTER 411 ECOFAST & COMBIMASTER 411 ECOFAST
D-91050 Erlangen	
Federal Republic of Germany	
Email: documentation.sd@siemens.com	Anwender-Dokumentation
1	
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